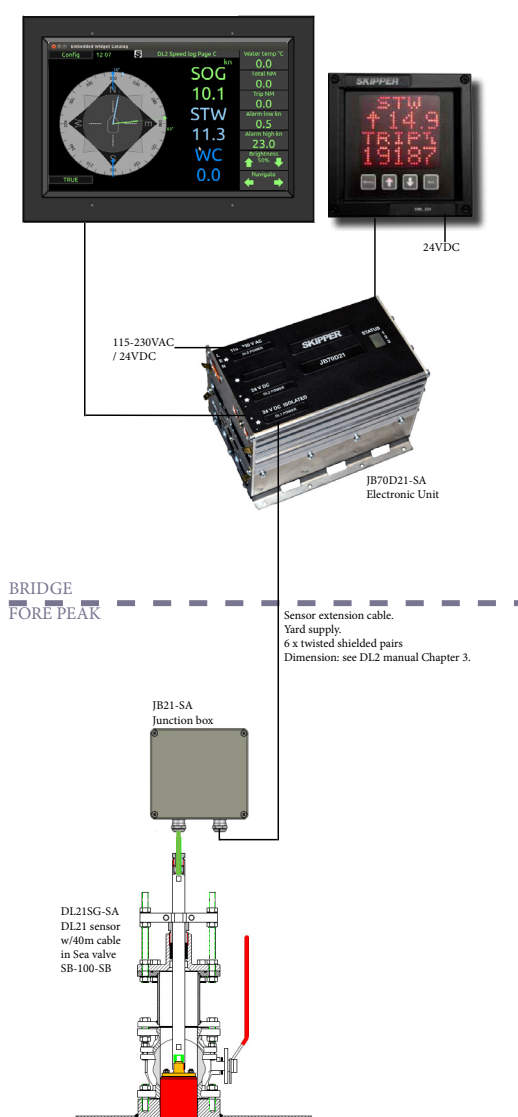


# SKIPPER

## DL21

### Installation Manual

## Dual axis Doppler Speed Log System (SOG+STW) for vessels >50.000GT.



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Document no: **DM-M006-SA**  
Rev: 2130  
For software ver 1.0.17  
Date: 2021-08-19

**DL21*****DUAL AXIS DOPPLER SPEED LOG SYSTEM***

# INSTALLATION MANUAL

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# TERMINOLOGY

## TERMS USED IN THIS MANUAL

### Units

Unless otherwise stated, all values shown on the display are as follows:

|                   |                    |
|-------------------|--------------------|
| Speed             | Knots              |
| Distance (Vessel) | Nautical miles     |
| Depth             | Meters             |
| Tilt              | ° Degrees          |
| Temperature       | ° Centigrade       |
| Rotation          | Degrees per minute |
| Heading           | Degrees            |


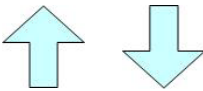
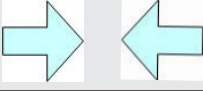
### Abbreviations


In addition, the following symbols are used



|       |   |
|-------|---|
| WT    | Water track   |
| BT    | Bottom track  |
| STW   | Speed through water   |
| SOG   | Speed over ground   |
| Trip  | Text for trip/total   |
| ECDIS | Electronic Chart Display and Information System                     |
| INS   | Inertial Navigation System  |
| VDR   | Voyage Data Recorder  |
| ROT   | Rotation from Gyro  |
| GYRO  | Gyroscopic heading / rotation sensor                                |
| HDG   | Heading   |
| DL2   | 2 Axis Doppler Log (with speed over bottom and Speed through water) |
| DL1   | 1 Axis speed through water sensor (part of DL21 system)             |
| DL21  | A system with combined DL1 and DL2 in the same housings             |
| UDP   | User Datagram Protocol.   |
| SFI   | System function Id  |
| LAN   | Local Area Network  |

### Symbols

In addition, the following symbols are used

|   |  |
|---|--|
|  | Indicating that the information presented is partly from the GPS input, and therefore not from this sensor. (Outputs may show invalid data in this mode) |
|  | Symbolising that the data presented is longitudinal (forward or backwards)   |
|  | Symbolising the data is transversal (port or starboard)  |

|   |  |
|---|--|
|  | <p>Symbolising the resultant speed direction</p> |
|---|--|

|   |   |
|---|---|
|  | <p>Simulator mode - The system is using a simulator to generate the speed and depth</p>                       |
|  | <p>Option - Mute mode. The system has a sync option activated and is currently being muted (No acoustics)</p> |

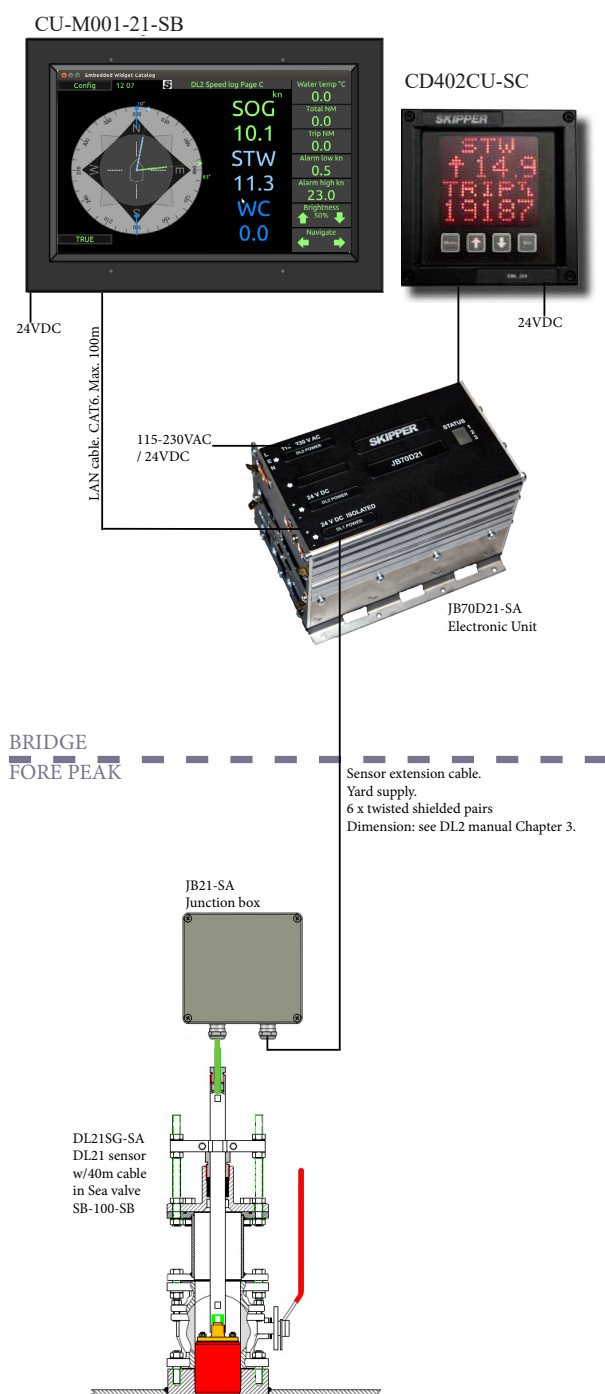
# CHAPTER 1: GETTING STARTED

## OVERVIEW DL21

The DL21 Doppler speed log is a Dual STW and SOG Navigational Doppler Speed log system. The new DL21 Speed Log is designed for ships over 50.000 GT with simultaneous and independent measurement of speed through water and speed over ground.

The DL21 is a DL1 (single axis STW) + DL2 (Dual axis STW + SOG), built into 1 sensor housing, 1 electronic unit and 2 Display units.

The system fulfills all class and type regulations based on MED B (wheelmark) and is manufactured in Norway under stringent production controls.



The DL21 system consist of:

2 x Operator units.

- CU-M001-21-SB for DL2
- CD402CU-SC for DL1

1 x Dual Electronic Unit  
JB70D21-SA Electronic unit

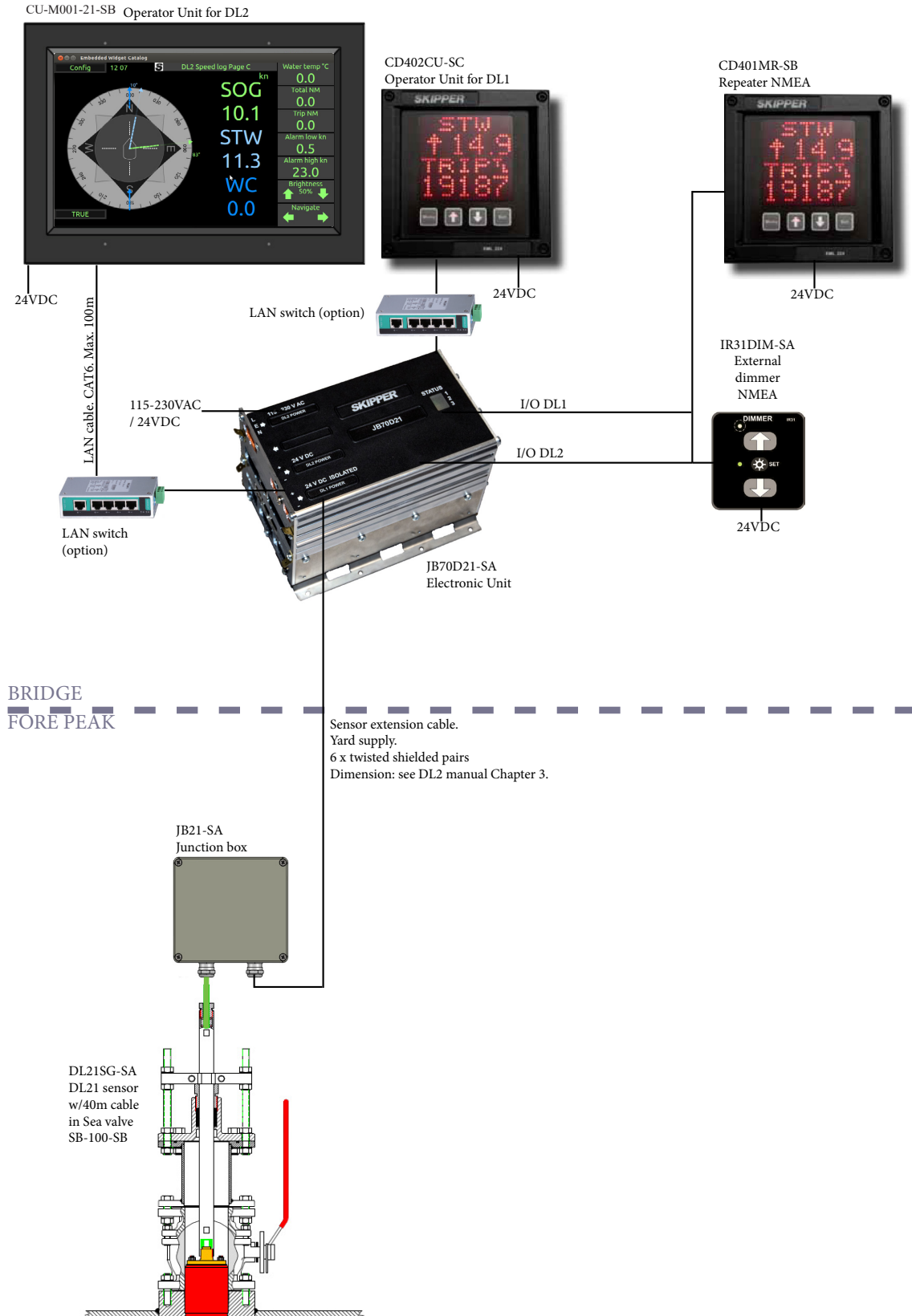
1 x Junction box  
JB21-SA  
(Optional for extension of 40 m sensor cable)

- 1 x Sensor DL21SG-SA
- 1 x (STW) Single axis + 1 x (STW + SOG) Dual axis sensor in one housing.
  - Fits into SB-100-XX/DB-100-XX sea valves

## OPTIONAL ITEMS DL21

The following items are optional SKIPPER supplied items.

- Speed Repeater
- External dimmer
- LAN switch



## ITEMS NOT SUPPLIED BY SKIPPER

The following items are not SKIPPER supplied:

- LAN cable (minimum CAT6) from Operator unit to Electronic unit.
- The sensor is manufactured with a 40m cable. The cable may be cut or extended. Extension cable is 6 pairs with individual screens. See chapter 3 for lengths and dimensions.

## POWER SUPPLY REQUIREMENTS

The JB70D21-SB power supply includes separate power for DL1 and DL2

### DL2:

- CU-M001-21-SA. Operator Unit. 24V DC. Max 10 W, Typical 6 W.
- JB70D21-SA. Electronic unit (DL2 Power): 24V DC and/or 115/230V AC. Max 60 W typical 15 W.

### DL1:

- CD402CU-SA. Operator Unit. 24V DC. Max 10 W, Typical 6 W.
- JB70D21-SA. Electronic unit (DL1 Power): 24V DC. Max 20 W.

There are no power switches on the CD402CU-SA, CU-M001-21-SB or JB70D21-SA.

The separate power inputs should be including a manual circuit breaker.

There are no input fuse on the CD402CU-SA, CU-M001-21-SB or JB70D21-SA.

The power input should be including a fuse rated for 100 % - 200 % of max power installed components.

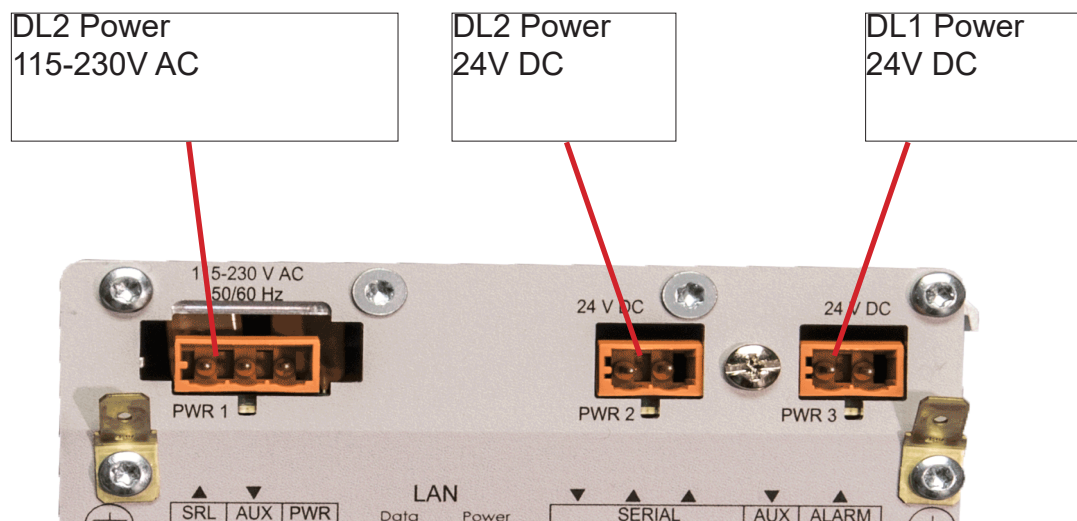
Example:

Two separate 24V supplies for DL1 and DL2.

Each 24V supply should have a 3A slow blow fuse.

Optional items power supply requirement:

- CD401MR-SB repeater. 24V DC. Max 10 W, Typical 6 W.
- IR31DIM-SA. External dimmer: 24V DC
- LAN switch: 24VDC



# CHAPTER 2: HARDWARE MOUNTING

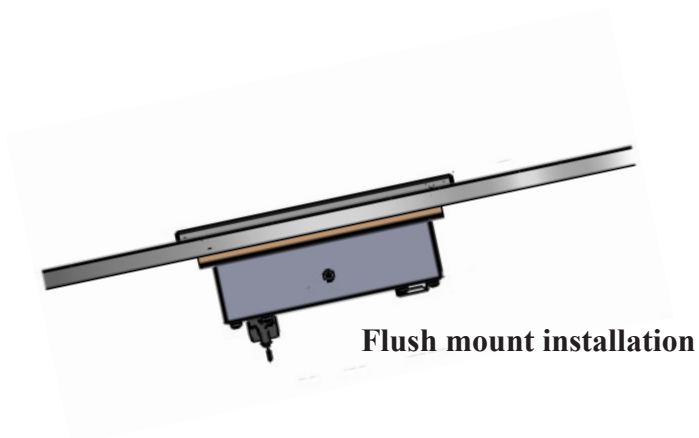


## PLACEMENT OF THE OPERATOR UNIT

The operator unit is placed on the bridge.

Some standards require some operations of the unit to be available from 'standing position'. These operations are available from the operator unit and multi-repeaters if both input and output are connected.

Dimensional drawings are found in Appendix 1.

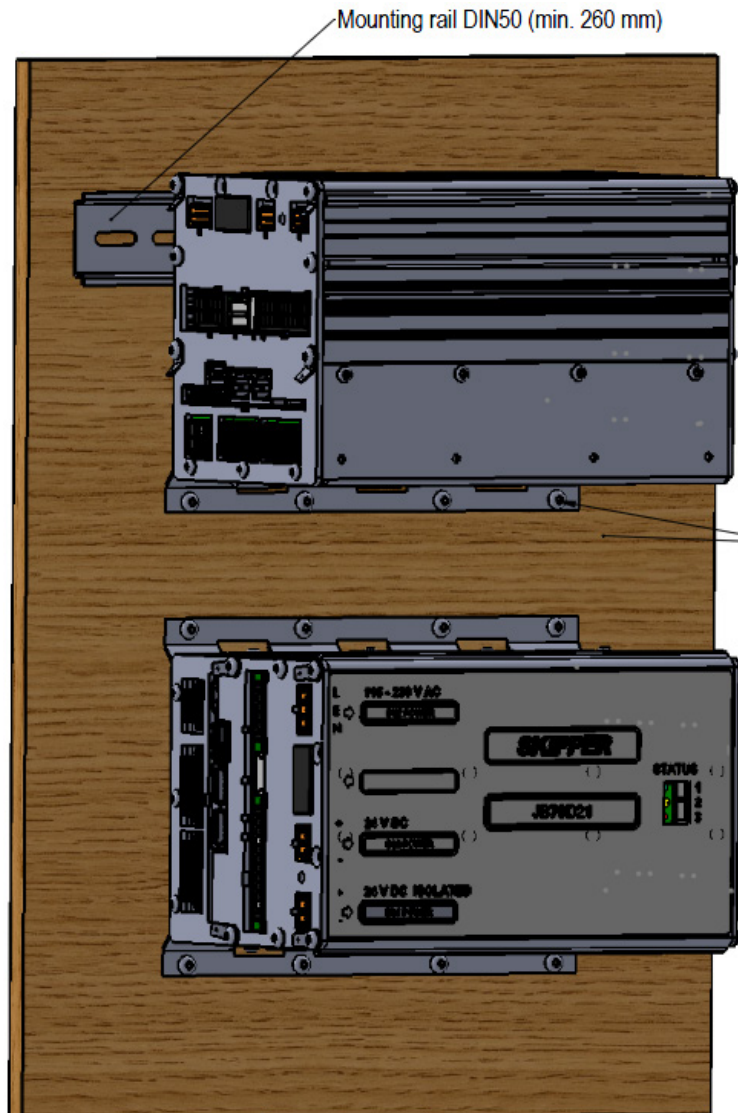


## PLACEMENT OF THE ELECTRONIC UNIT

The electronic unit can be installed on a DIN rail or directly screwed onto the wall.

All parts of the system are connected to the electronic unit.

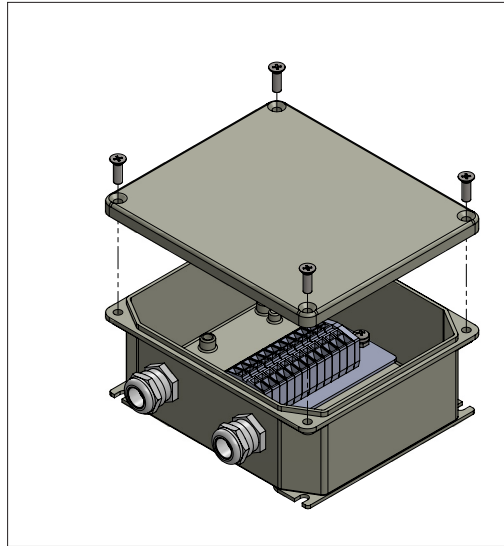
There are no buttons (like ON/OFF) in the electronic unit. Access is only required for service purpose. Placement is typically in or near the bridge where the interfaced systems are available, but no nearer than 0.5 m to the GYRO heading sensor. IP rating: IP20.



## PLACEMENT OF JB21 JUNCTION BOX

The junction box JB21 is an option for connecting sensor cable to a yard supplied extension cable (See chapter 3).

It is placed in a dry place within reach of the 40m sensor cable.



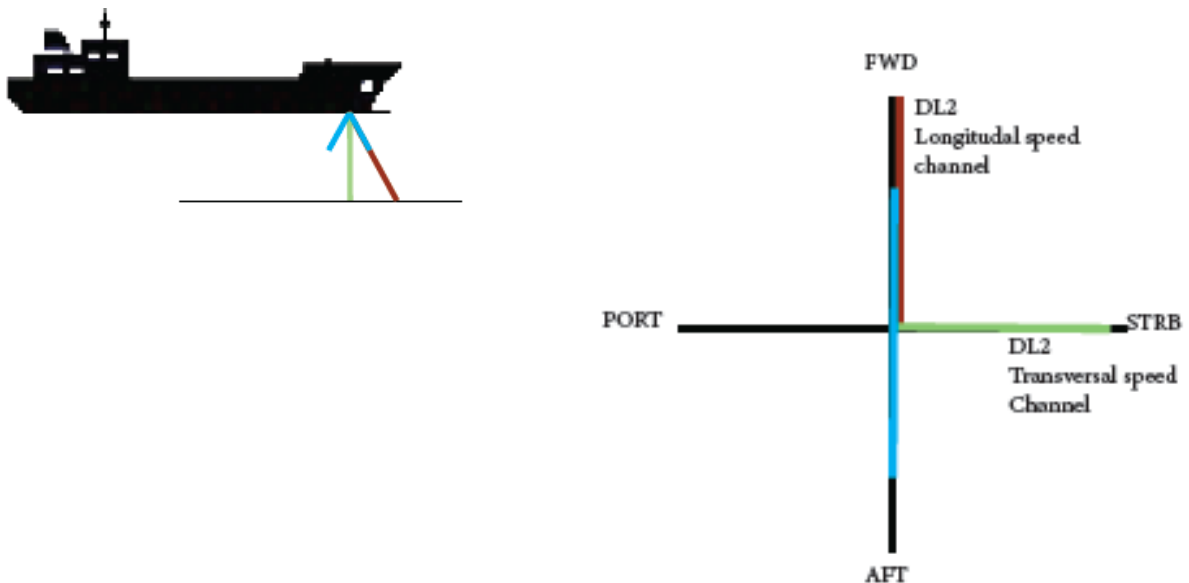
## PLACEMENT OF REPEATERS

Repeaters are typically installed on the overhead console and/or the bridge wings. These can be routed using NMEA signals. These require a local +24 V DC supply. Please note that STW NMEA output from DL1 part and SOG NMEA is from DL2 part.

## PLACEMENT OF THE SEA VALVE

Mounting instructions for the sea valve is available from the SKIPPER web site in separate manual depending on the chosen type. When placing the speed log sensor, consider the following moments:

- Free sight to the bottom (it should be possible to draw a cone of  $\pm 45$  degrees from the sensor to the bottom).
- The active face of speed sensor must be in parallel to the horizontal line, max offset  $\pm 1^\circ$ .
- Do not mount transducers aft of bow thruster, propeller outlets or aft of other hull installations (such as outlets, vents or other protruding details) that may create aeration or turbulence.
- It is necessary to select a part of the hull that is submerged and free from turbulence and aeration under all load and speed conditions, and to avoid positions where air is trapped in heavy weather.
- If a flat, horizontal section is not available for transducer fitting, the shipyard must construct a suitable bed. Welding seams in this area and forward should be smoothed and rounded off in order not to create turbulence or aeration and maintain a laminar waterflow at all speed ranges of the vessel.
- Select an area that is acoustically quiet. The DL2 operates at frequencies between 270 kHz and 284 kHz. The DL1 between 710-720kHz.



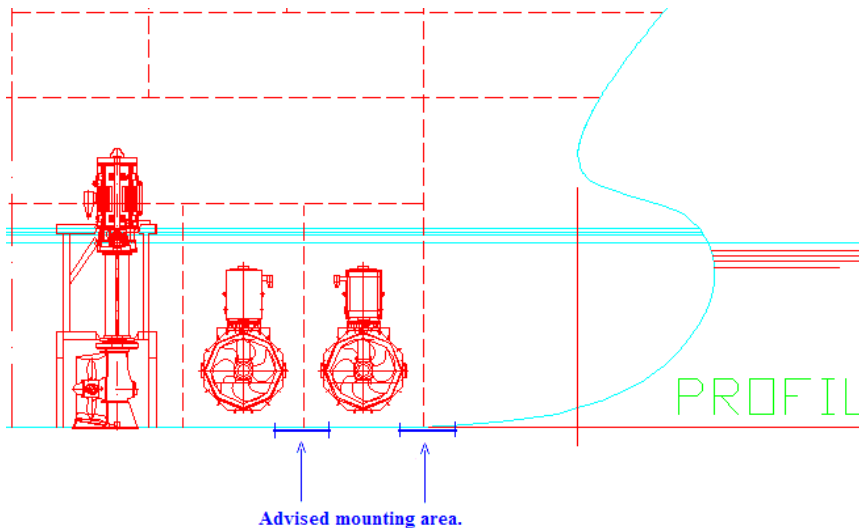
There are 4 acoustic channels in DL21

DL1 has 2 channels (Blue forward and blue aft)

DL2 has 2 channels (Brown forward and Green starboard).

The acoustic signal is sent in a 30deg angle from vertical.

A tilt sensor internally inside the DL21SG-SA sensor is used to compensate for vessel movement.



The generally best placement on larger vessels is in the front region of the vessel just behind the bulbous bow (see fig above). This area is generally designed such that the bubbles are pushed to either side of the bulb, leaving a clear area under the bulb and just behind. The sensor is installed in a sea valve in order to service the sensor (clean or replace) without docking the vessel.

It is recommended (but not required) to install the sea valve in a dry area, like a bow thruster room. This will enable easy cable access to junction box and additionally increase the lifetime of the sea valve.

## PLACEMENT OF THE SENSOR IN SEA VALVE

The sensor DL21 is installed into sea valve 100mm for single bottom SB-100-SB or double bottom DB-100-SB.

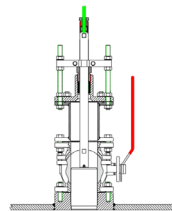
Please see sea valve manual for installation procedure.

Manuals available as downloads from [www.skipper.no](http://www.skipper.no)

The sensor includes 40m moulded in cable. The cable is 11 mm in outer diameter with a bending radius of 56 mm. The cable can be cut or extended if required



**SB-100-SB**  
Operation and Installation Manual

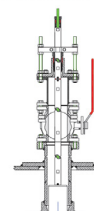


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Document no: SB-100-SB-08 Rev 1.00A  
Edition: 2008.03.17



**DB-100-SB**  
Operation and Installation Manual



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## NOTE

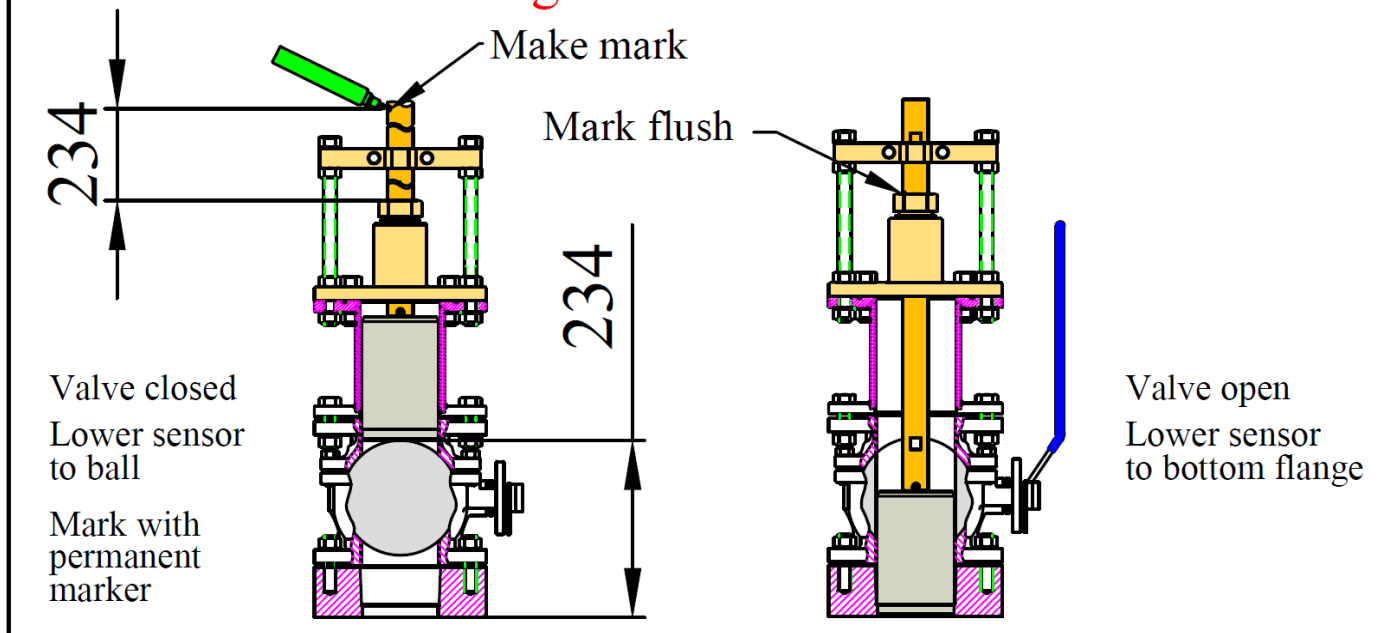
During physical installation of sensor into sea valve please make special care of the following points:

- Sensor to be lowered completely into bottom flange making sensor head flush with outer hull.
- Sensor forward direction to be aligned  $\pm 10^\circ$ . (Fine adjust by software in calibration page)
- Clamping unit nuts and nut M50 to be tighten to secure sensor position.

Sensor lowered flush with outer hull.

Pictures showing lowering procedure in sea valve SB-100-SB.

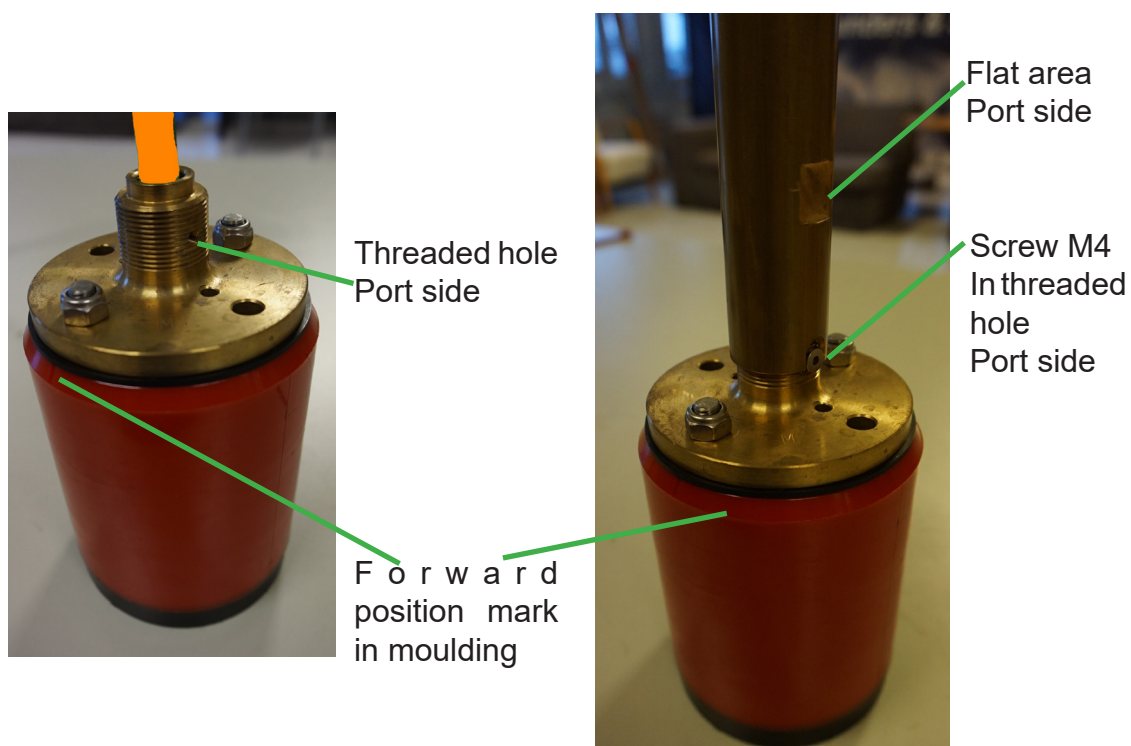
## Procedure for installing of sensor in Sea valve SB-100-XX

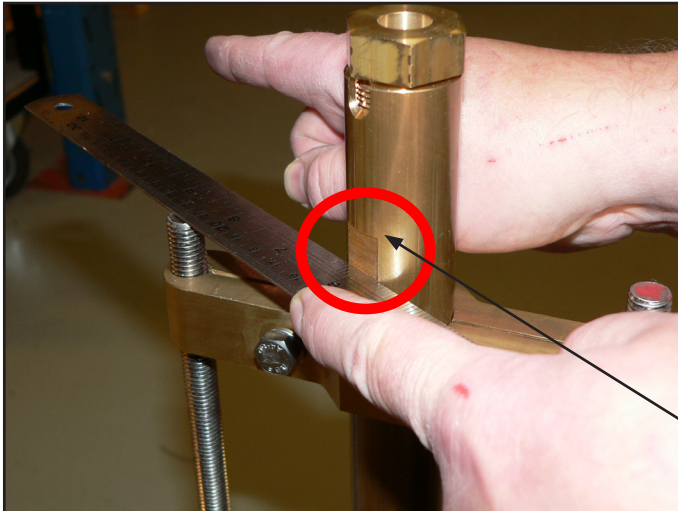


Sensor forward direction.

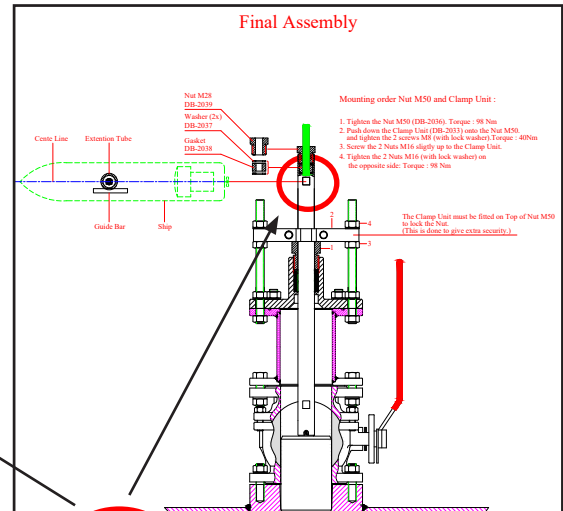
It is important to align sensor forward direction.

Pictures showing forward direction alignment in sea valve SB-100-SB.



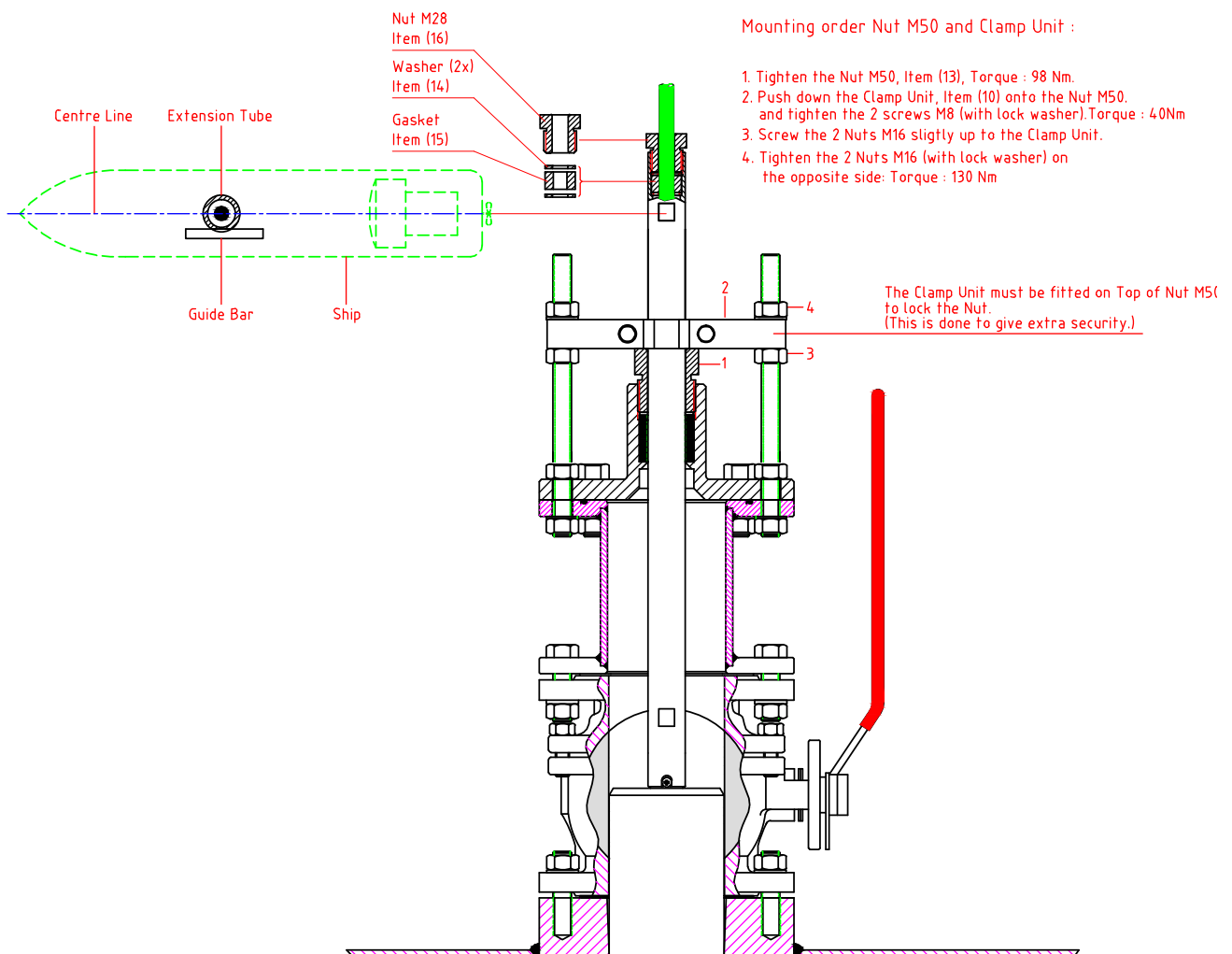


A flat object points fore/aft.



The flat side should be on the port side.

Secure sensor by tightening clamping unit and nut M50



## CHAPTER 3: WIRING

Two separate 24VDC supplies are required

The JB70D21-21-SA does not contain a physical switch and should be connected to a circuit breaker. Power may be nominal 24V DC (No more than 32V DC) and/or 115-220V AC. Max 60W typical 15W. The AC input is an optional back up for DL2 part of JB70D21-SA only.

There are no input fuse on the CU-M001-21-SB or JB70D21-SA.

The power input should be including a fuse rated for 100% - 200% of max power installed components. Example: A 24V DC to power both CU-M001-21-SB and JB70D21-SA should have a 3A slow blow fuse.



### CLAMPING THE CABLES

Cables should be connected to WAGO connector, leaving approximately 3 cm of tail. They should be stripped with 6-7 mm of metal showing and these should be connected as in the diagram above. A small screwdriver with blade size approx 3.5 mm can be used. WAGO part no 210-719 is ideal for this use.

Outer shields should be collected and grounded in a ground stud on the edge of the cabinet. The outer insulation should be cable tied to the plastic handle of the connector, and securely anchored nearby. The plugs when refitted, must be installed such that their clips are fully in the up position.

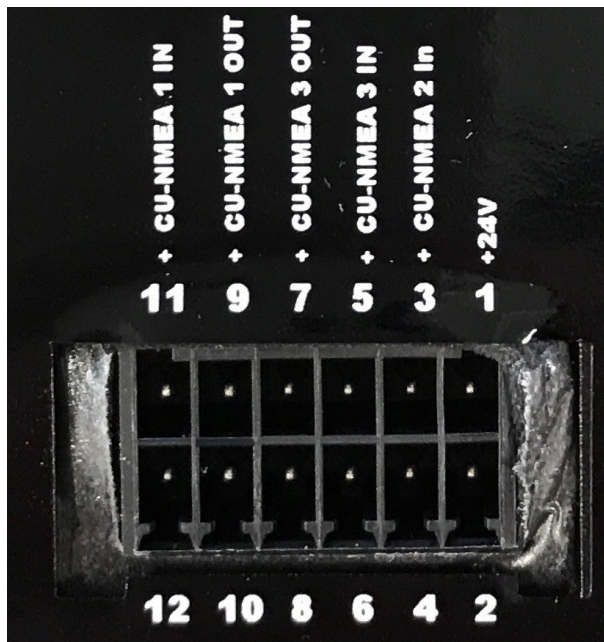
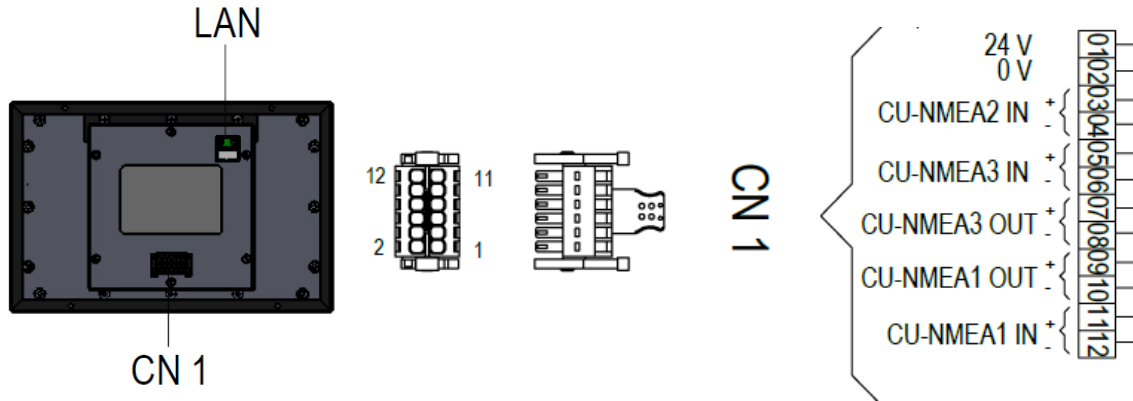


## CU-M001-21-SB OPERATOR UNIT WIRING

The operator unit has 2 connectors.

1 LAN connector for communication with Electronic unit.

2: WAGO connector CN1 for 24V power. Max 10W, Typical 6W.



Note:

CU-NMEA only in use for parallel systems. See appendix 4.  
Standard NMEA I/O on  
JB70D2-SA

Items supplied with CU-M001-21-SB

1 x ZZN-01120.

Connector Female w/ejectors 6x2 pole, black. (CN 1)

1 x ZZN-01123. Strain relief plate, 6x2 pole, width 11 mm. (CN 1)



## JB70D21-SA ELECTRONIC UNIT WIRING

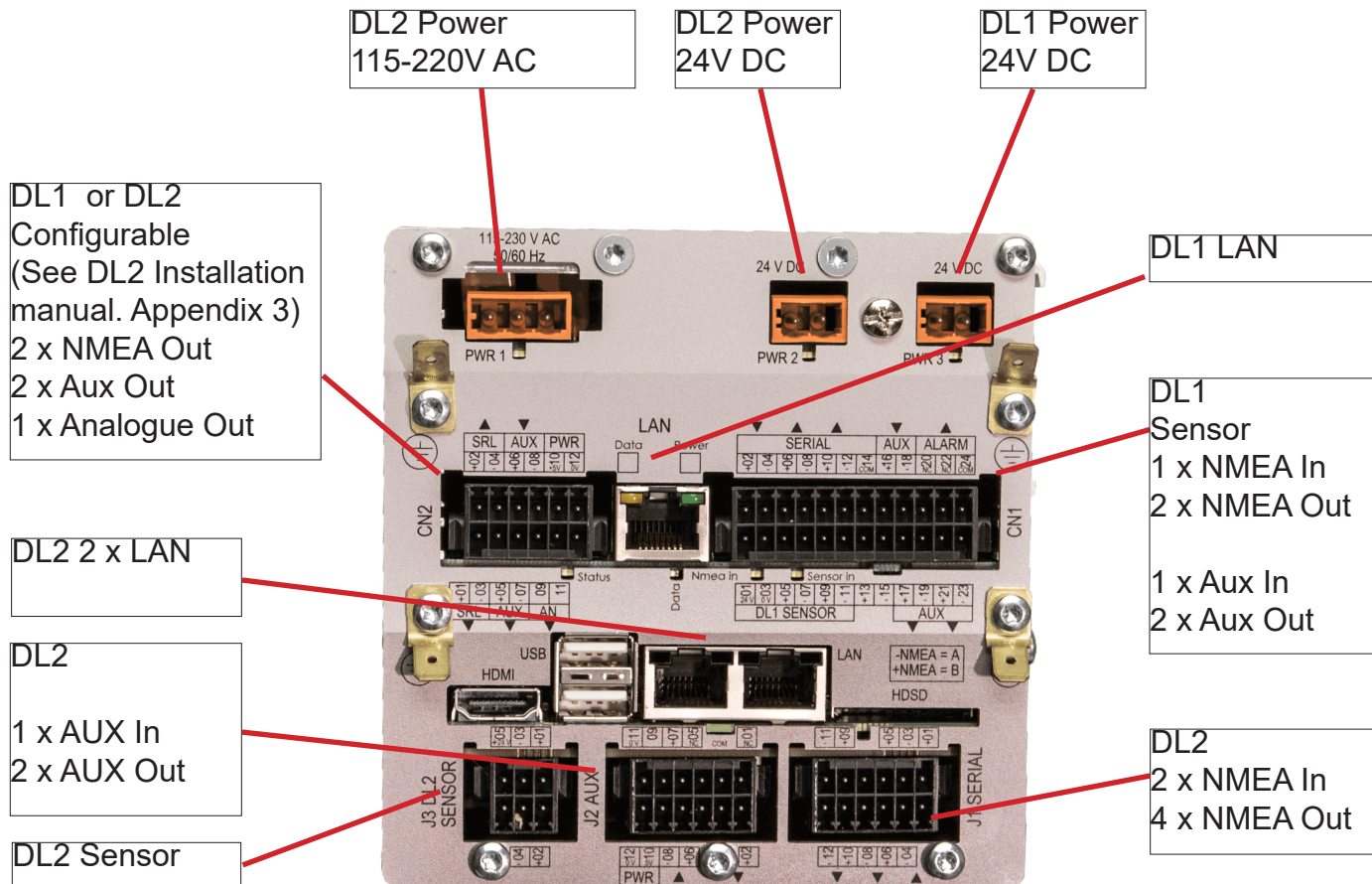
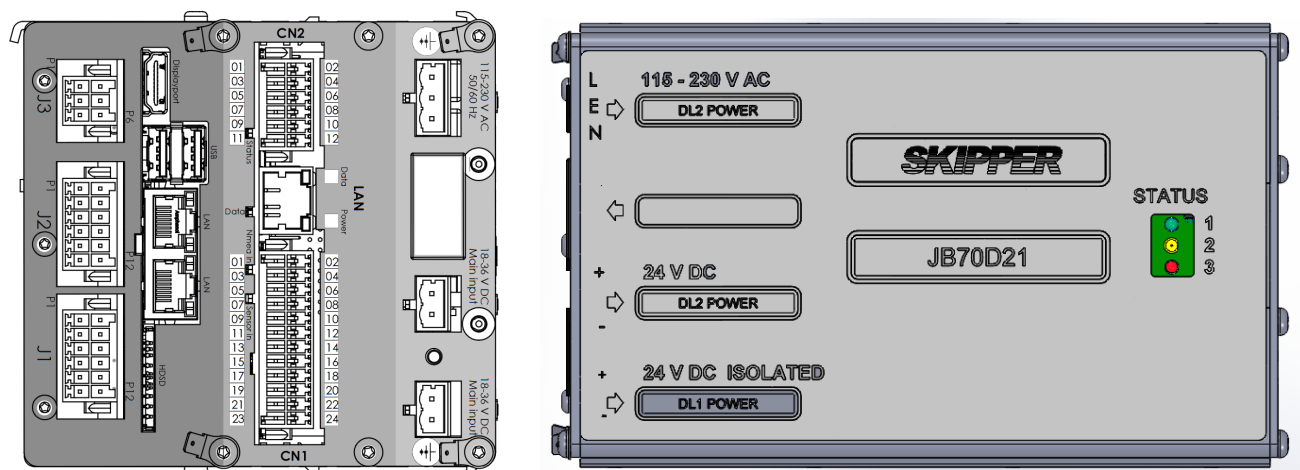
The JB70D21-XX does not contain a physical switch (only software) and should be connected to a circuit breaker for removal of power.

The DL2 is powered from nominal 24VDC (Max 32VDC) and/or 115-230V AC.

The DL1 is powered from 24V DC Isolated input.

For wiring of DL1 Operator unit (CD402) please see "Installation manual DL1" DM-M004.

For wiring of DL2 Operator unit (CU-M001) please see "Installation manual DL2" DM-M002.



## CONNECTORS SUPPLIED WITH JB70D2



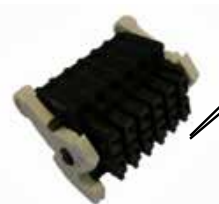
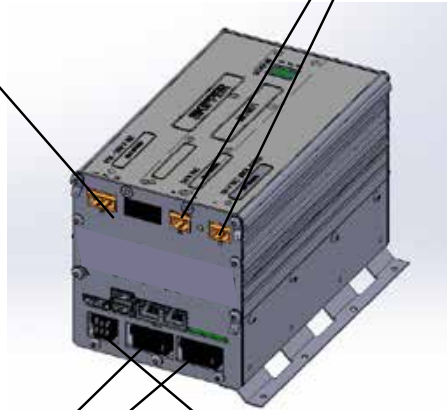
ZZN-01126 Relief Housing,  
3 pole snap-on.  
WAGO: 232-633



ZZN-01124 Plug, Female 2  
pole, 231-302\_032-000



ZZN-01136 Plug, Female  
3 pole with locking levers,  
231-303/037-000



ZZN-01120 Connector Fe-  
male w ejectors 6x2 pole, black  
WAGO 713-1106/037-000



ZZN-01130 Connector, Fe-  
male w/ejectors 3x2 pole, black  
WAGO 713-1103/037-000



ZZN-01123 Strain relief  
plate, 6x2 pole, width 11 mm  
WAGO 713-126



ZZN-01123 Strain relief  
plate, 6x2 pole, width 11 mm  
WAGO 713-126



## NMEA CONNECTION

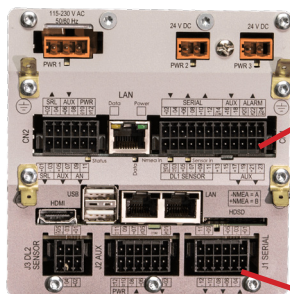
The DL21 is in fact two individual speed log systems. When connecting I/O to external devices it is important to consider the alternative methods.

### Recommended alternative 1

DL1 sending STW in VHW (or VBW) sentence. Trip in VLW sentence

DL2 sending SOG in VBW sentence.

This alternative is making a clean border between DL1 as a STW and DL2 as SOG speed log. It will however require a receiver with 2 NMEA inputs.



DL1 NMEA out  
VHW + VLW



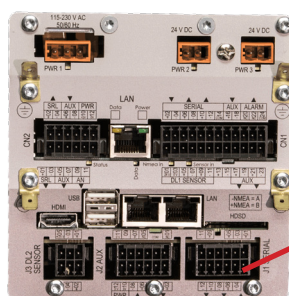
DL2 NMEA out  
VBW



### Recommended alternative 2

DL2 sending SOG, STW in VBWX sentence. Trip in

This alternative is possible because DL2 is receiving STW and trip information internally in the system from DL1. The VBWX sentence is a proprietary SKIPPER sentence used only by DL2 in a DL21 system to transmit STW, SOG and Trip from one NMEA output



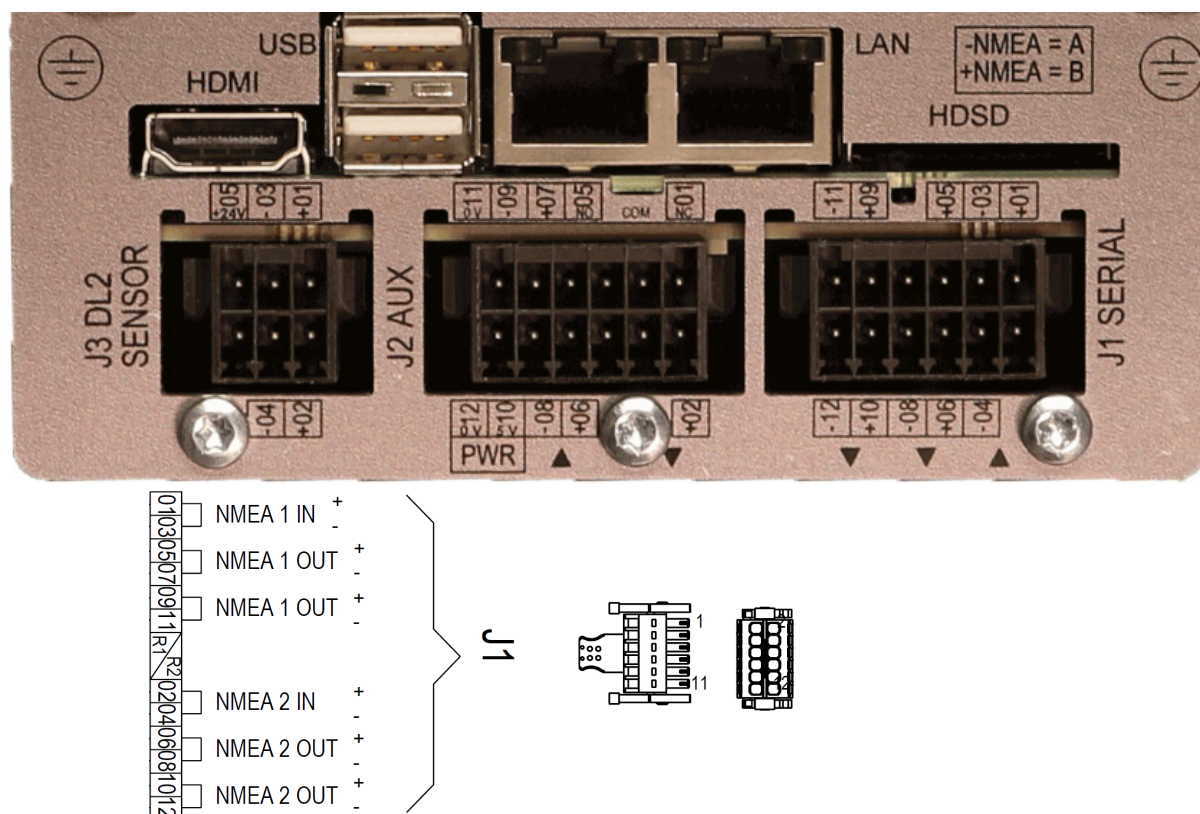
DL2 NMEA out  
VBWX+VLW



## NMEA CONNECTION

SOG may be transmitted from the DL2 VBW sentence. DL2 has standard 2 NMEA Inputs and 2 Outputs.

Each output is dual and makes total of 4 outputs.

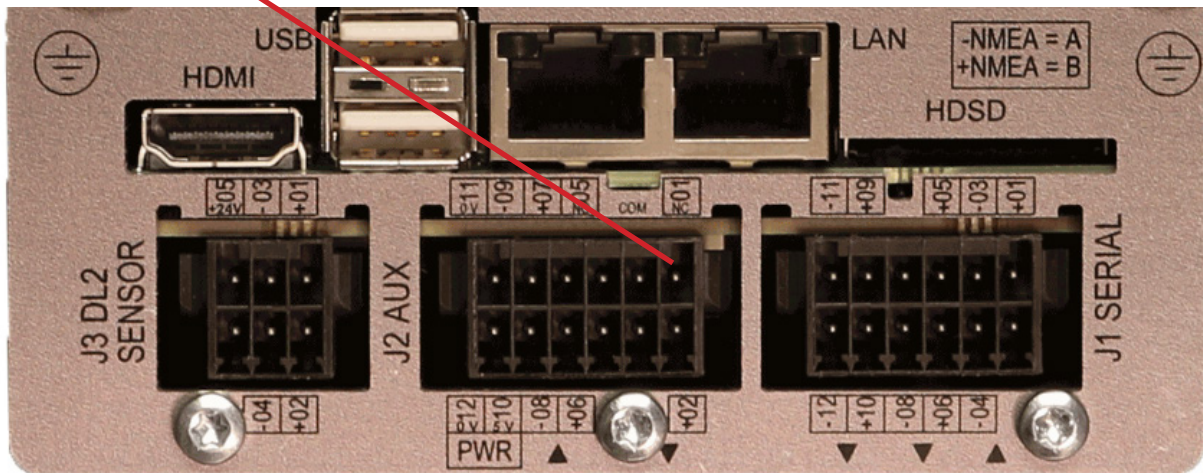
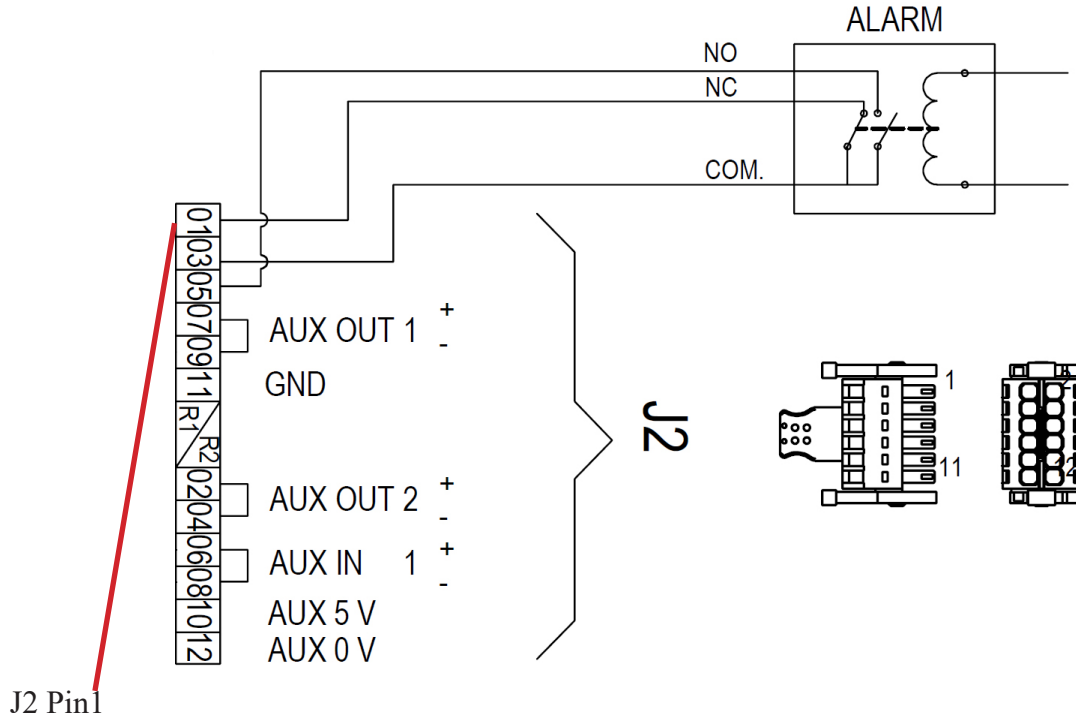


If high speed protocols are to be used (IEC61162-2) the communication common (COM) can be connected to pins 11 or 12 of J2

## AUX/ALARM CONNECTION J2

The DL2 has standard

- Alarm relé
- 1 x Aux In.
- 2 x Aux Out.



## ADDITIONAL NMEA, AUX AND ANALOG OUT

An optional Multi Extension PCB is required for additional NMEA, additional Aux or analog output. See Appendix 3.

**YARDSUPPLIEDEXTENSIONCABLEFROMSENSORTOJB70ELECTRONICUNIT.**

Any screened 3 or 4 twisted pair cable can be used as long as the loop resistance (measured by twisting the pair together at one end and measuring the resistance) is less than 8.6 ohms (worst case).

**Example1:**

What kind of cable do I need for 300m distance from sensor to Electronic unit?

300m cable (0.3km). Loop length  $0.3 \times 2 = 0.6\text{km}$ .  $8.6/0.6 = 14.3\text{ Ohms/km}$

Use a cable with maximum 60 Ohm conductor DC resistance per km.

AWG15 / 1.5mms has resistance of 10.4 ohm /km

**Example2**

I have a CAT7 cable. Spec says 70 Ohm conductor DC resistance per km. How long distance from sensor to Electronic unit can I use this cable?

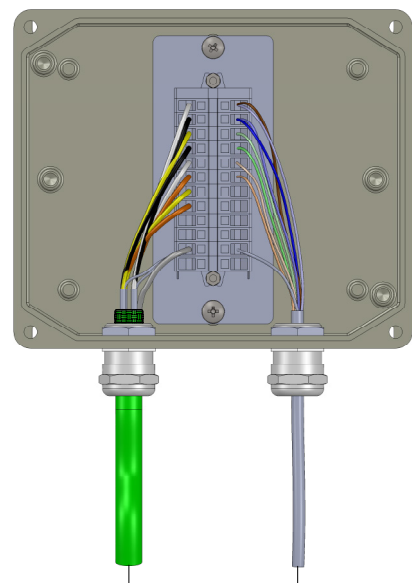
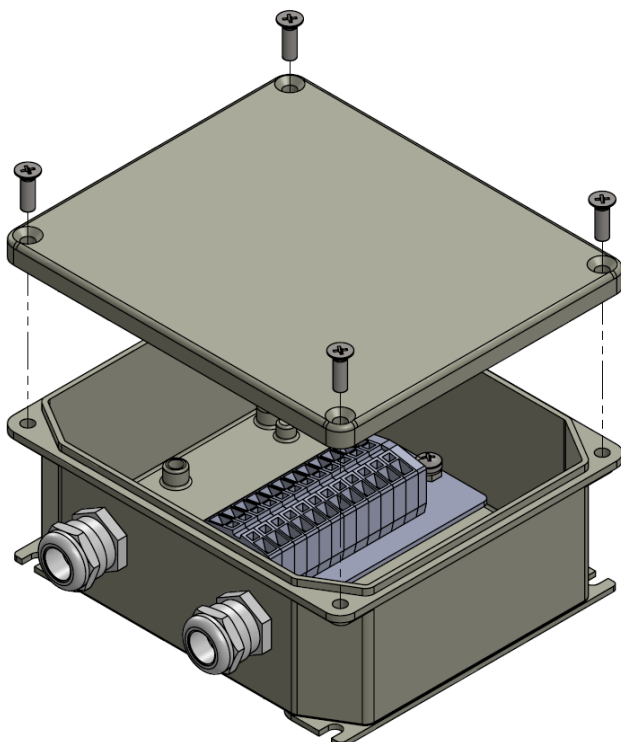
$8.6/70 = 0.122\text{km}$ .  $0.122\text{km}/2 = 60.1\text{m}$  maximum length.

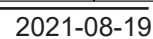
**THE JUNCTION BOX (JB12)/SPLICE**

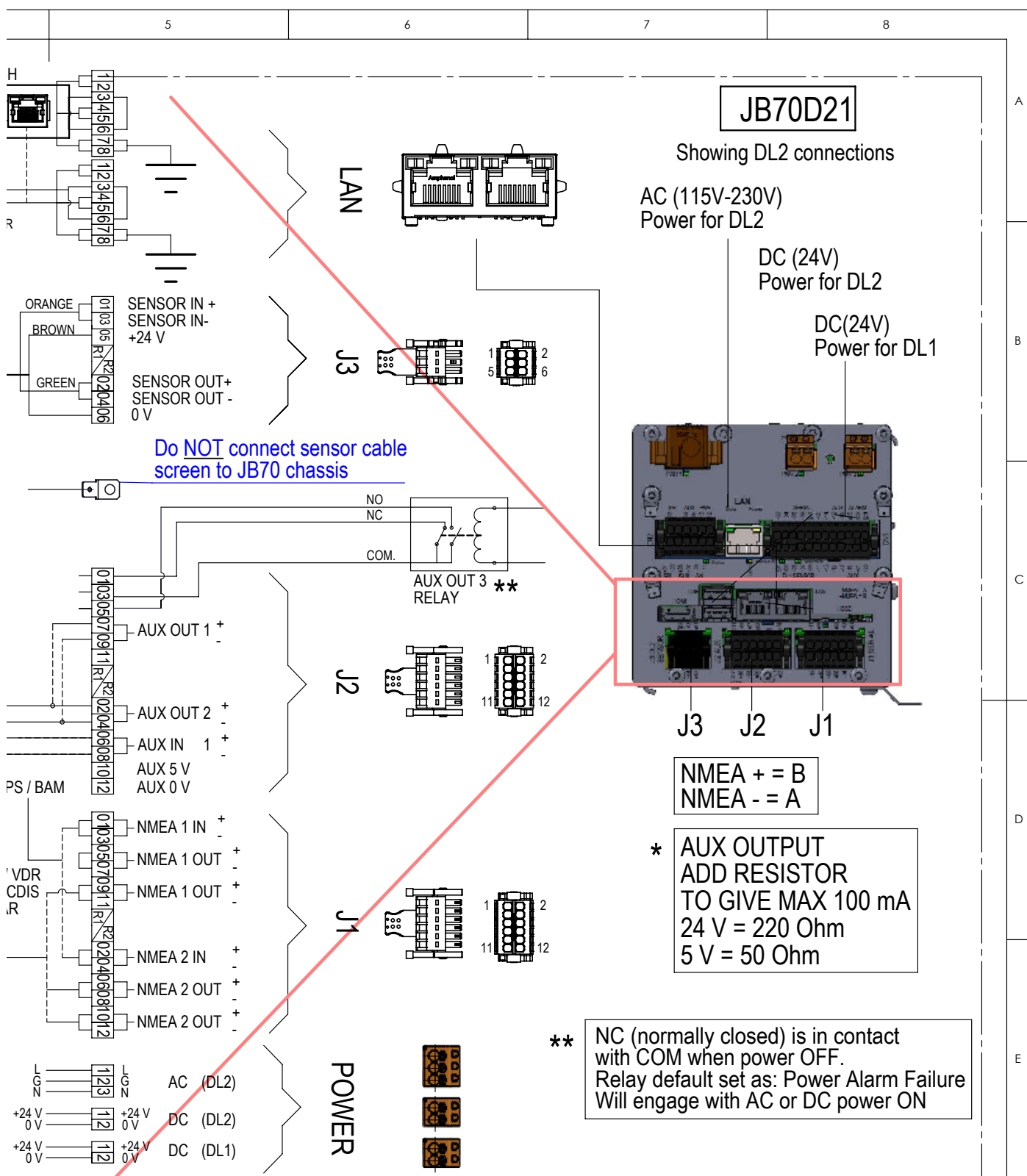
The JB12 Junction box may be used as a terminal between sensor cable and an extension cable. Dimensional drawing see Appendix 1.

All individual screens of sensor cable to be connected to the outer screen of the CAT7 extension cable.

Do not ground screens to JB12 chassis.







|                                  |   |  |  |   |                         |
|----------------------------------|---|--|--|---|-------------------------|
| CN                               | 2018.09.28 ST CU-M001-SB connector change. Changed value on AWG table | Rev.02. Changed grounding on LAN and JB12/JB21 ST 2021.02.15 | Explained AUX 3 OUT better ST 2021.03.22 |   |                         |
| Designed by - date               | Checked by  | Approved by - date   | Material                                 | Name Wiring diagram for DL21 Multi<br>Showing DL2 connections |                         |
| ST 2015.04.20                    | GT  | GT 2018.09.28  |  |   |                         |
| <b>SKIPPER</b><br>Electronics AS |   |  | Drwg. no.                                | CD-2038   | Revision 02             |
|                                  |   |  | Gen. tolerance                           | Eur. projection   | Scale                   |
|                                  |   |  | ISO2768m                                 |   | Edition date 2021.03.22 |
|                                  |   |  |  |   | Sheet 1 of 2            |

# CHAPTER 4: SETUP PROCEDURE

Setup of communication JB70D2-SA to CU-M001-SB

The communication between operator unit and Electronic unit is following IEC61162-450 lightweight ethernet standard.

This standard allows the network to be used for the distribution and control of sensor systems such as the DL2. These communicate using proprietary NMEA type messages on this multicast (UDP) system. The system will exert a maximum load on the network of 20 kB/s (kilobyte per second), and will tolerate a data traffic up to 20Mbit/s (Megabit per second)

An advantage of this method of communicating is that it becomes simple to have more than 1 display unit on the same system. Instead of (or as well as) repeaters, the user can have as many control units as they wish. These are activated by pairing the units to the electronic unit. In the case of INS bridges, the main bridge conning unit can be used as a control unit as well or instead of the screen (with approval).

The following parameters must be set on both units before communication is established:

- IP address
- SFI
- Paired SFI (only for Operator unit CU-M001-SB)
- Group

**IP Address:** The IP address of the system should not clash with any other system within the network. Regulations state that the IP address range. During setup, it may be necessary to change the IP to fit into your local network. recommended subnet is 255.255.255.0

**SFI (System Function ID):** Each device has its own identifier (SFI) and the systems can then identify who they are and who they are talking to. These should be unique within a vessel.

**Paired SFI:** Each Operator unit CU-M001-SB device needs to know which system it is part of. By entering the SFI of the JB70D2-SA the system pairs itself.

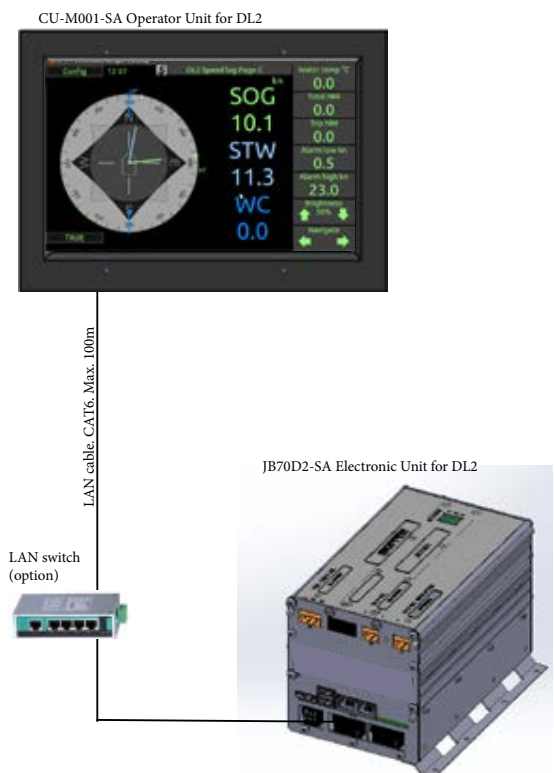
It is possible to have multiple screens to a single JB70D2-SA unit. All screens will work in parallel.

**Group:** There are 8 groups available for the system to be part of. It is important that the group is the same on all communicating devices. NAVD, VDRD,RCOM,TIME,PRO P,MISC,TGTD,SATD,

**NOTE:** The following procedure will take you through the setup using the operator unit CU-M001. It is important to change the JB70D2-SA group before the CU-M001-SB group otherwise you will loose connection

The setting of IP address, SFI, Paired SFI and Group on JB70D2-SA is also accessible from SKIPPER service software by connecting a PC to the second LAN port or via a LAN switch.

SKIPPER service software is available in download folder on [www.skipper.no](http://www.skipper.no)

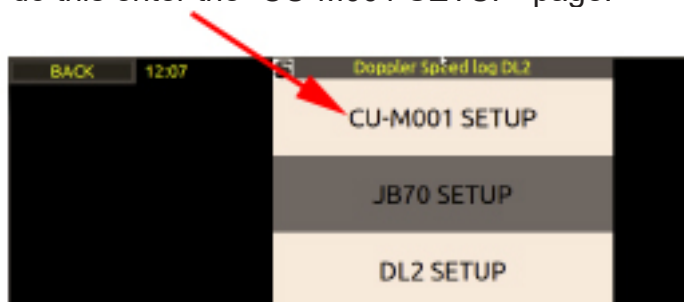


## CONFIG

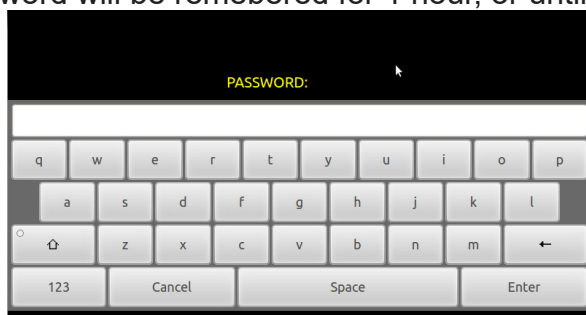
Setup pages are accessed by pressing “CONFIG”



First, the Operator unit CU-M001-SA must be connected to the main Electronic Unit JB70D2-SA. To do this enter the “CU-M001 SETUP” page.



To enter and adjust these screens a password is required. The password for all units is ‘service’. The password will be remembered for 1 hour, or until reboot of the system.



## CU-M001 SETUP

On starting the display CU-M001 first time it will try pair up with a JB70D2-SA.

Default settings:

**Screen:** Horizontal (no vertical available)

**System type:** DL2/DL21

**IP Address:** 172.16.1.102

**SFI (System Function ID):** II0102

**Paired SFI:** VD101(default SFI of JB70D2-SA)

**Group:**NAVD.

**SUBNET:** 255.255.255.0

**Dimming:** Rx

**NOTE:**

If connected to LAN network please make sure IP addresses, SFIs and Group is approved by local administrator.

If 2 x DL2/DL21 systems are to be installed on same LAN then IP address SFI and paired SFI have to be changed on (at least) one of the systems to avoid conflict of settings.

If default values have to be replaced then please change IP address of JB70D2 before changing on CU-M001.

|   |              |   |
|---|--------------|---|
| <b>BACK</b>   | <b>12 07</b> |   |
| <b>SYSTEM TYPE: CU-M001</b><br><b>SERIAL NUMBER: 14001</b><br><b>ID: II0012</b><br><b>GROUP: NAVD</b><br><b>IP ADDRESS: 192.168.0.99</b><br><b>APPROVED IP RANGE:</b><br>172.16.0.1 to 172.31.255.254<br><b>CURRENT SYSTEM TYPE: DL2 / DL21</b><br><b>SOFTWARE VERSION 1.0</b><br><b>UPLOAD DATE 01.01.2015</b> |              | <b>SCREEN</b> Horizontal<br><b>SYSTEM TYPE</b> DL2 / DL21<br><b>IP ADDRESS</b> 192.168.0.99<br><b>LOCAL SFI</b> II0012<br><b>PAIRED SFI</b> VD0029<br><b>GROUP</b> NAVD<br><b>REMOTE DIMMING DDC</b> Rx |

Remote dimming DDC

Off

The screen can be dimmed on screen.

Rx

The screen can be dimmed on screen or using a remote DDC message. The system can be made to accept remote dimming from the local input or the JB70 input.

Tx

The screen can be dimmed on screen or using a remote DDC message. The system can be made to accept remote dimming from the local input or the JB70 input.

It can also be made to send a DDC message when the dimming level is changed.

**JB70D2 SETUP**

|  |  |
|--|--|
| <div>BACK 12 07</div> <div>SYSTEM TYPE: JB-70</div> <div>SERIAL NUMBER: 99999</div> <div>ID: VD0029</div> <div>GROUP: NAVD</div> <div>IP ADDRESS: 192.168.0.97</div> <div>APPROVED IP RANGE:<br/>172.16.0.1 to 172.31.255.254</div> <div>ALARM SFI: AS1234</div> <div>SOFTWARE VERSION 1.0</div> <div>UPLOAD DATE 01.01.2015</div> | <div>IP ADDRESS 192.168.0.97</div> <div>LOCAL SFI VD0029</div> <div>GROUP NAVD</div> <div>Alarm SFI AS1234</div> |
|--|--|

Default settings:

**IP Address:** 172.16.1.101  
**SFI (System Function ID):** VD0101  
**Group:**NAVD.  
**SUBNET:**255.255.255.0

When on this setup page, the user is setting parameters on the remote device. It is therefore important that the devices are properly connected before adjusting here. If the devices are not connected you will see a system alarm on screen. Pressing this symbol will show which alarm is active.

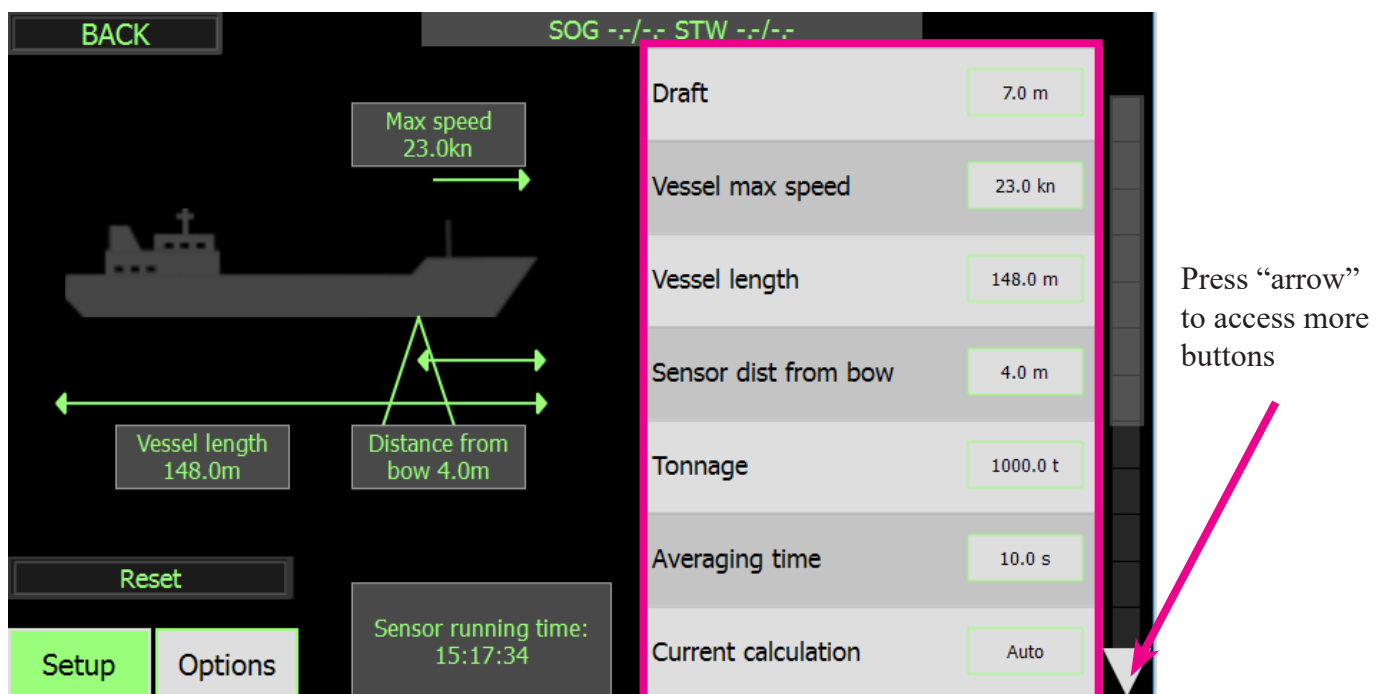
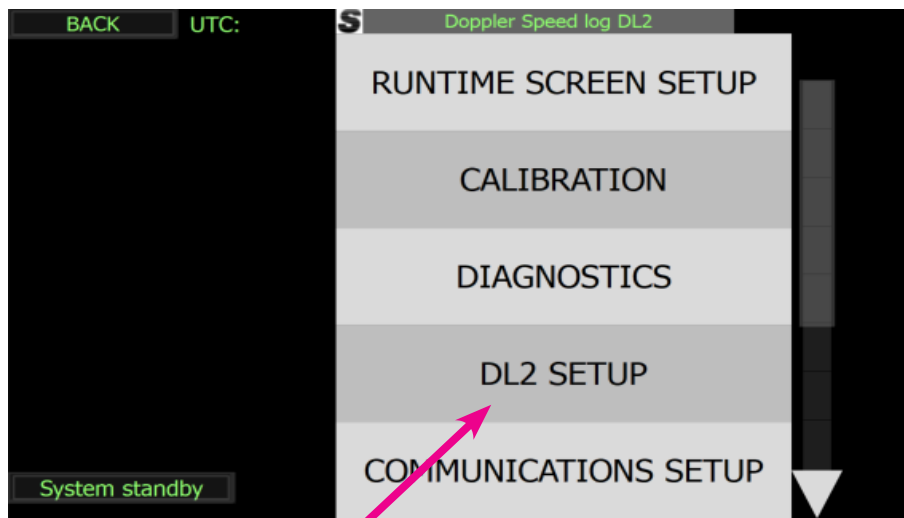
This process can also be performed in a simpler way by using the Communications Application available in the SKIPPER service software (available for download on the SKIPPER website.)

This App allows you to connect to the same network as the units and then perform a search. The software will show you all the connected units, and you may then edit the IP adress, SFI and group from the software. You may then enter the web pages for each individual unit.

## DL2 SETUP

To help the system to calculate accurate a number of parameters should be setup for the specific vessel it is installed into. These are entered in the DL2 setup menu.

DL2 setup is accessible from the “config” menu.



| Button                       | (default) options                     | What it is used for  |
|------------------------------|---------------------------------------|--|
| Draft                        | (meters) feet fathoms                 | Used to make the depth value show from the surface and not from the sensor.  |
| Vessel Max Speed             | (knot) m/s mi/h                       | Used to set the calibration parameters and to ensure data is reasonable.   |
| Vessel Length                | meters                                | Used to calculate The Aft transversal speed (ROT signal must be input for this)  |
| Sensor distance from Bow     | meters                                | Used to calculate The Aft transversal speed (ROT signal must be input for this)  |
| Tonnage                      | tonnes                                | Used to set correct averaging time. Larger vessels will have slower speed changes and may use a higher averaging to calculate the speed.   |
| SOG Averaging time           | seconds                               | Manuel set of averaging time for SOG at speeds over 6kn. This setting will override settings from “Tonnage”  |
| SOG low speed averaging time | seconds                               | Manuel set of averaging time for SOG at speeds under 6kn. This setting will override settings from “Tonnage”   |
| STW averaging time           | seconds                               | Manuel set of averaging time for STW at speeds over 6kn. This setting will override settings from “Tonnage”  |
| STW low speed averaging time | seconds                               | Manuel set of averaging time for STW at speeds under 6kn. This setting will override settings from “Tonnage”   |
| Current calculation          | (AUTO)<br>Log-SOG,<br>GPS-SOG<br>AUTO | The “Water current” speed and direction are calculated from the STW measurement and an SOG from the log and/or a GPS input. In deep water,(depths>150m) SOG is not available from the log. AUTO will automatically change from log to GPS when log bottom is lost.<br>Log-SOG will allways calculate “Water current” with SOG from log.<br>GPS-SOG |
| GPS on lost bottom           | (ON)/OFF                              | If the water is too deep, the system cannot measure SOG. This option will switch the value to GPS (on screen) with a small symbol to indicate where the data comes from.<br>The system will not send SOG data on its outputs in this case.   |
| Vessel image                 | 1-5                                   | The image of a vessel can be changed to various vessel types.  |
| SOG Shallow ping length      | 1-(2)-4-8msec.                        | Default 2msec.<br>May be set to 1msec for better shallow water   |
| SOG Deep ping length         | 1-2-4-(8)msec.                        | Default 8ms for deeper bottom tracking   |
| SOG Shallow power            | Low-Medium-(High)                     | Default High. Power level of SOG signal in shallow water   |
| DL1/DL2 synch                | OFF / (ON)                            | In DL2 the systems can be made to ping simulataniously to prevent acoustic cross over  |
| Sampling Distance            | (0.5)-16m                             | The STW water sample can be moved further from the vessel to reduce effects of drag.   |
| Low speed correction         | (ON) off                              | activation of a filter to improve alongside data.  |

|                        |                       |   |
|------------------------|-----------------------|---|
| Output parameters      | SOG+STW<br>SOG only   | <p>If the system is configured as a DL21, it should be configured such that the STW parameter to radars etc comes from the DL1 part, and the SOG comes from the DL2 part. To ensure this the button SOG only / SOG+STW is set, and then disables the STW parts of the DL2. Instead the DL1 STW (single axis) still be displayed on the screens.</p> <p>The outputs will change so that STW is not available in the VBW NMEA sentence on the DL2, but is available on the VBW from the DL1</p> <p>If a single set of repeaters is to be used. The SKIPPER Multi repeater CD401MR-SB can be used ,and set up so that it shows SOG from the \$VDVBW sentence , and STW from the DL1, which is retransmitted through the DL2 in the \$VDVHW sentence or all together in the special \$PSKPVBW sentence.</p> <p>To do this configure Screen 1 on the repeater to SOGL and SOGT, and Screen 2 to STW-R. In the DL2 activate either VBW and VHW or VBWX.</p> |
| Primary STW Frequency  | (High freq), Low freq | The STW parameter can measure at both high (850-910kHz) and low (265-278kHz) frequency. High is normally better, but the user can change to low frequency. Both frequencies are calibrated during a Sea test calibration, and the Current primary is displayed in the Calibration settings as default.  |
| SOG Freq. Change point | (0) 0-10m             | The SOG parameter is also improved in shallow water by using the high frequency. This value is the depth at which the SOG starts using the high frequency   |

### Important settings at time of installation:

**Vessel max speed.** Please insert before first time speed calibration. Calibration may be lost if Max speed is changed.

**Vessel length and Sensor distance from bow.** Required for Aft transversal speed calculation.

**Tonnage** and averaging time: Response time of speed log should be set correct to the specific vessel. Normally response is relative to tonnage of vessel. A default averaging time is set on basis of tonnage input but the averaging time may be manually adjusted independant of tonnage.

### Saving settings on USB Stick:

Once settings have been setup it is possible to save the settings by inserting a USB Stick. This will create (or Use) a folder called /skipper/downloaded\_setups and in this folder it will create a directory with the DL2 system serial number

### reloading settings from a USB Stick:

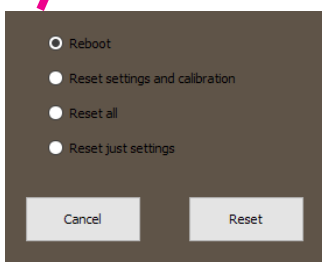
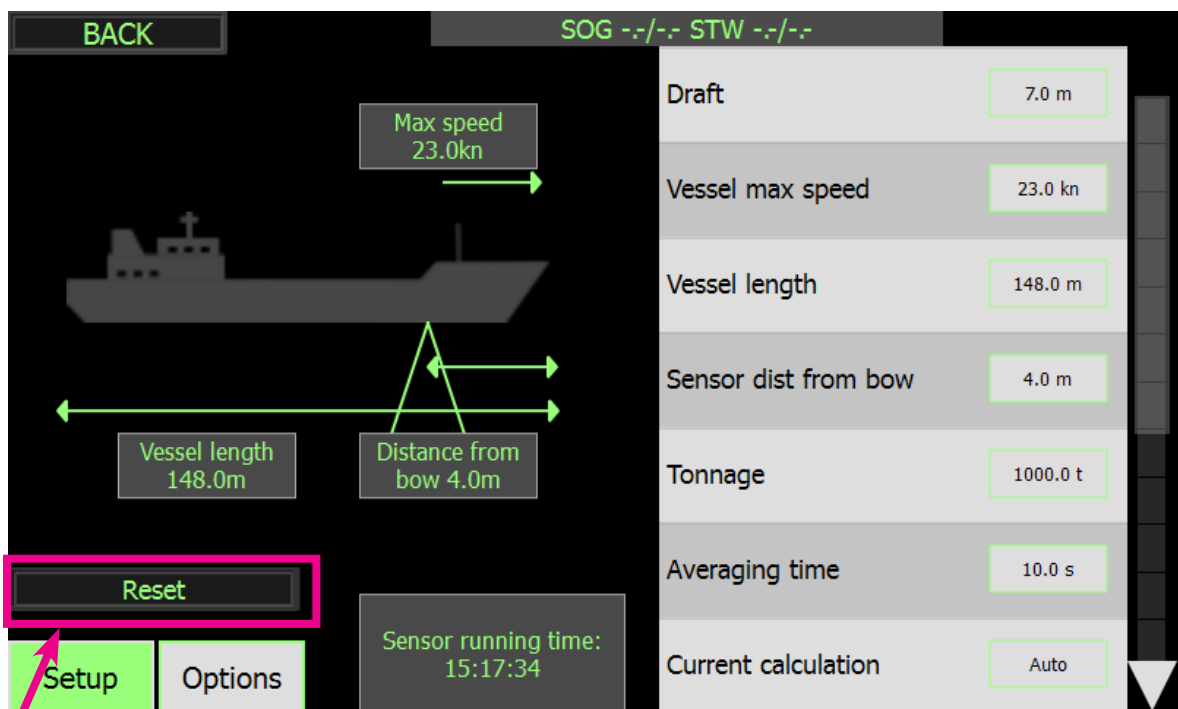
To reload a setting the directory with the serial number must be copied into a directory under /skipper/upload\_new\_setup/

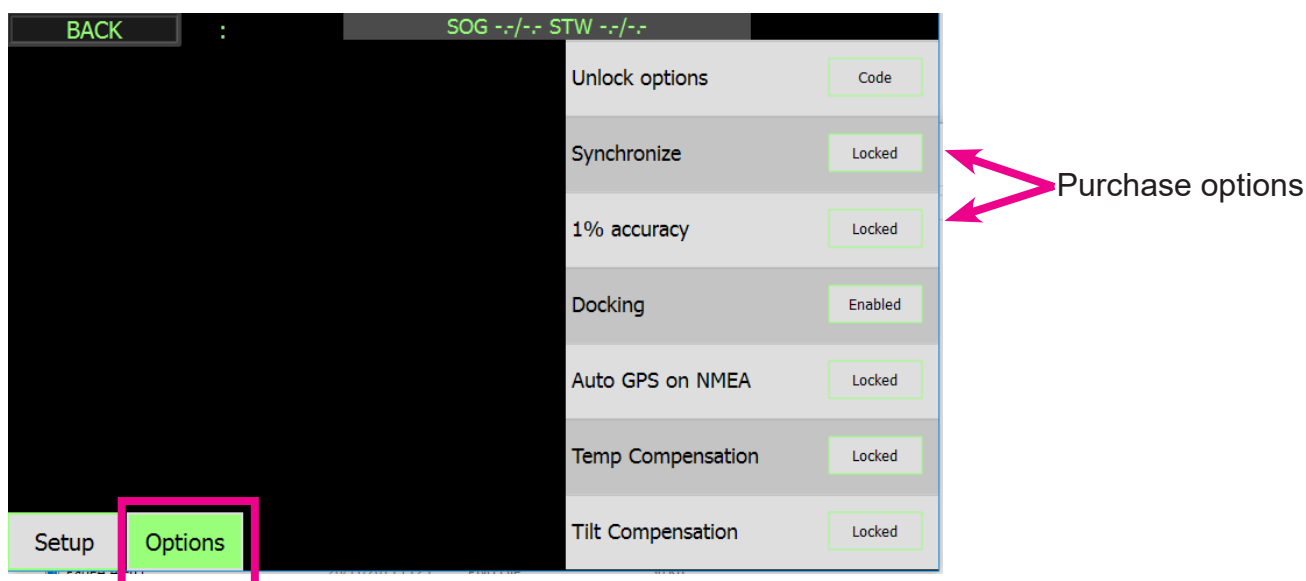
This will be copied into any system the USB stick is placed. Wait until the system has rebooted before removing

## RESET

There are 4 available reset options.

1. Reboot of software
2. Reset settings: Will reset settings for NMEA, AUX and DL2 setup back to default.
3. Reset settings and calibration: Will also set calibration settings to default.
4. Reset all: Will set the system calibration and communication settings (IP) back to default





## SOFTWARE OPTIONS

The DL2 system has a number of options available. The software and hardware in this product is designed to meet the requirements of MED and IEC 60945. The product in its standard form is limited to meet the specification required. However, it is designed to allow adjustments and improvements to be implemented so that the product can be used in markets requiring higher specification and functions not standard in a commercial speed log.

There are currently 2 available purchase options. These are activated by entering the code provided by SKIPPER in the correct field. All options can be activated in retrospect (at an additional cost) by giving the system serial number to SKIPPER, they will send the activation code in return

### Purchase options

#### - 1% accuracy

DL2 is default 2% accuracy. Activating 1% accuracy option will give the option in the DL2 menu, and in each NMEA output menu, to configure to show 1 or 2 decimals, on the screen values and NMEA sentences.

Will enable a set of filters and features that will ensure and check, that the unit is operating within 1% specification.

#### - Synchronize

This option enables the user to send a mute signal to stop the sensor from pinging.

There are 2 synchronize input options:

- AUX level into the aux input to stop the sensor.
- NMEA message input \$PSKPBLNK,2,1,ON\*nn or \$PSKPBLNK,2,1,OFF\*nn where ON is mute

There are 2 synchronize output options:

- AUX "SyncOut" will give a pulse out when sensor is confirmed muted from external input.
- AUX "PingOut" will give a pulse out when sensor is pinging.

Please note!

The sensor pinging is a very short repeating pulse of 1-8 milliseconds.

Due to electronics delay the sensor will mute 8ms after a level change on the Aux input.

When Synchronize is active a warning M will be shown on the screen, after 10 seconds of mute, the system will detect this as a sensor failure and give a system alert.

**Non-Pay options**

Docking

Auto GPS on NMEA

Temp compensation

Tilt compensation

**Activating/de-activating software options.**

Software options can be activated and de-activated in the DL2 menu. This page contains a table where the installer can enter codes purchased/supplied from SKIPPER. Codes will only activate if they detect the correct hardware in place. Codes are unique to the serial number of the system and can not be moved from system to system. To remove an extra option, the user must re-enter the code number.

## COMMUNICATIONS SETUP (NMEA/UDP)

### NMEA

The most common communication method to this type of system is the IEC61162-1 NMEA ports, these use an isolated input RS422 differential method. The IEC61162-1 standard requires 4800 baud, 8 databits, 1 stop bit and no handshake. The system also supports faster communications as specified in the IEC61162-2 standard using 38400 baudrate. If this standard is to be used the output requires a common connection available on J2 pin 11 or pin 12.

It is also possible to run the system at 115200 baud, although there is no standard to support this.

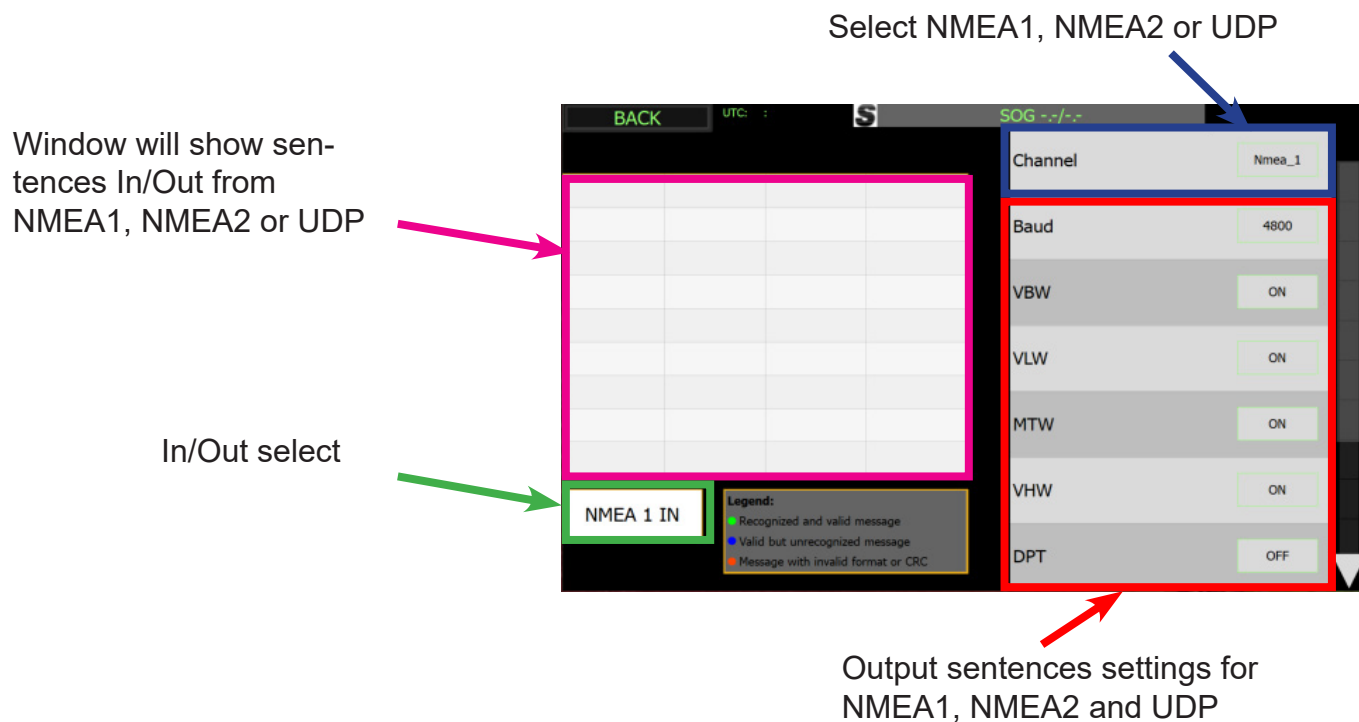
### LAN UDP

In addition, this unit supports the LAN UDP standard (IEC61162-450 (2018))

Communication setup page is accessed via config menu.

Scroll down with the right sid arrow until “Communication setup” button is displayed.

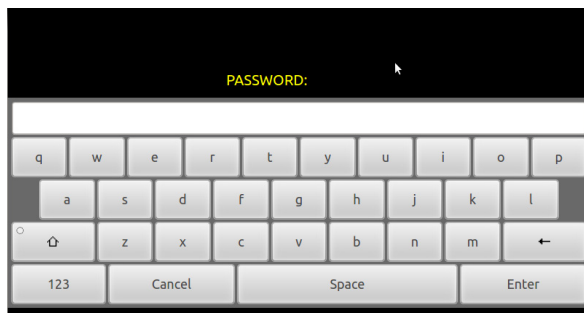




For each of the outputs 1, 2 and LAN (UDPM) it is possible to activate a number of sentences. Normally with On and Off. The resulting outputs are shown on the left on the screen.

Output settings are password protected for changes.

The password for all units is 'service'. The password will be remembered for 1 hour, or until reboot of the system.



## NMEA SENTENCES RECEIVED

If input is shown, then the system will colour code the headers to show if the data is recognised, and correct, recognised and not correct, or not recognised/used

All channels will detect inputs and automatically use those that are recognised

### Time

|                  |   |
|------------------|---|
| Day, month, year | ZDA,hhmmss.ss,xx,xx,xxxx,xx,xx*hh<CR><LF> |
|------------------|---|

### Position

|                      |   |
|----------------------|---|
| Geographical lat/lon | GLL,llll.ll,a,yyyy.yy,a,hhmmss.ss,A,a*hh<CR><LF>                    |
| GPS position         | GGA,hhmmss.ss,llll.ll,yyyy.yy,a,x,xx,x.x,x.x,M,x.x,xxxx*hh <CR><LF> |

### Rate of Turn

|              |  |
|--------------|--|
| Rate of turn | ROT,x.x,A*hh<CR><LF> (Required for docking.) |
|--------------|--|

### Heading

|                         |                       |
|-------------------------|-----------------------|
| Heading, true, present  | HDT,xx.x,T*hh<CR><LF> |
| True heading and status | THS,x.x,a*hh<CR><LF>  |

### Composite

|                       |   |
|-----------------------|---|
| Loran C specific      | RMA,a,xxxx.xx,N,xxxxx.xx,W,,,xx.x,xxx.,,*xx<CR><LF>               |
| GPS, transit specific | RMC,hhmmss.ss,A,llll.ll,a,yyyy.yy,a,x.x,x.x,xxxxxx,*,*hh <CR><LF> |

### External trip reset over NMEA

|  |  |
|--|--|
| Trip reset<br>In SOG only mode Trip reset to DL2 will be transferred to DL1. | \$PSKPRSTT*,<hh><CR><LF>               |
| Trip and total adjust  | \$PSKPSTL,<trip>,<Total>*,<hh><CR><LF> |

### External dimming over NMEA

|                                  |                             |
|----------------------------------|-----------------------------|
| External dimming of display unit | \$--DDC, a, xx,a*hh<CR><LF> |
|----------------------------------|-----------------------------|

### Placing a system in standby

|                                    |  |
|------------------------------------|--|
| Set a system in standby or wake up | \$PSKPSLP,<target SFI>,<sleep value>*hh<br>command added for setting system to sleep or waking up.<br><target SFI> can be JB's SFI or SFI of a display paired with JB of a particular system, <sleep value> is "1" or "0", "1" - sleep |
|------------------------------------|--|

A number of proprietary inputs may also be present (particularly on the LAN channel) to communicate with the display and JB70 unit

**NMEA SENTENCES TRANSMITTED**

(talker) (IEC 61162-1:2007(E) (NMEA 0183) messages:

**Speed and distance**

| Name        | Description   | Example   |
|-------------|---|---|
| <b>VTG</b>  | Course over ground and ground speed   | \$VDVTG,,,,,x.x,N,x.x,K,a*hh<CR><LF>                |
| <b>VHW</b>  | Water speed and heading<br>In SOG only mode VHW will show water trip and total from DL1   | \$VDVHW,,,,,x.x,N,x.x,K*hh <CR><LF>                 |
| <b>VLW</b>  | Dual ground/water distance<br>In SOG only mode VLW will show water trip x.x and total y.y from DL1, and Ground total a.a and Ground trip b.b from the DL2 | \$VDVLW,x.x,N,y.y,N,a.a,N,b.b,N*hh<CR><LF>          |
| <b>VBW</b>  | Dual ground/water speed<br>in SOG Only mode VBW first field will show data from DL1 STW   | \$VDVBW,x.x,x.x,A,x.x,x.x,A,x.x,A,x.x,A*hh <CR><LF> |
| <b>VBWX</b> | Dual ground DL2/water DL1 speed<br>As VGW with DL1 speed and validity in the last 2 fields  | \$PSKPBWx,x,x,x,A,x.x,x.x,A,x.x,A,x.x,A*hh <CR><LF> |

**Temperature**

| Name       | Description       | Example                  |
|------------|-------------------|--------------------------|
| <b>MTW</b> | Water temperature | \$VDMTW,x.x,C*hh<CR><LF> |

**Alarm**

The DL21 does not contain any function alerts, the power failure relay may be used if required.

**Depth**

| Name       | Description | Example                    |
|------------|-------------|----------------------------|
| <b>DPT</b> | Depth       | \$IIDPT,x.x,x.x*hh<CR><LF> |

Values will be preceded with sign as needed ( e.g “-“ = Astern, Port).

\*hh = Checksum.

**ALARM/ALERT SETUP**

Wheelmark (MEDB) Speed Logs have no requirement for alerts. The DL21 Alerts were removed in SW version 1.2.0.0 and above. This is due to the complexity of the newer IEC62934-2018 BAM standard. The DL2 stand alone system does contain alerts.

The Power failure relay is operational.

## SETUP AUX

The Auxiliary inputs and outputs can be assigned to different functions in the AUX Setup screen.

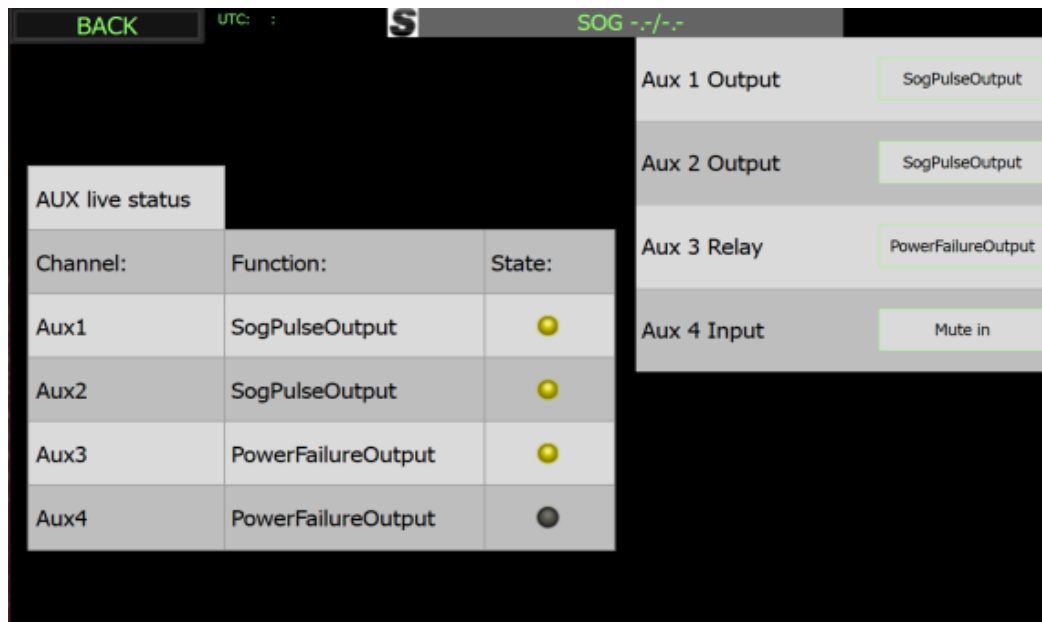
If Speed warning is selected on one of the output channels, then the user can set a high and low limit. At this speed the state of the output will change.

The current state of the AUX input and outputs are shown in the table below

| Name         | Type          | Pin numbers (J2 Aux) |
|--------------|---------------|----------------------|
| Aux 1 Output | Opto-isolator | 7 +, 9 -             |
| Aux 2 Output | Opto-isolator | 2+, 4-               |
| Aux 3 Relay  | Relay         | 1 NC, 3 Com, 5, NO   |
| Aux 1 Input  | Opto-isolator | 2+, 4-               |

Speed warning changes the output state as the vessels speed passes a set speed, this can have 2 values low and high. These values are set using below buttons.

**NOTE.** Aux 3 Relay output cannot be used for pulse speed output as the relay has a limited number of switching cycles.



Options for the Auxilliary output are.

| Option         | Description   | Option Code required? |
|----------------|---|-----------------------|
| STWPulseOutput | 200 PPNM showing STW                                | No                    |
| SOGPulseOutput | 200 PPNM showing STW                                | No                    |
| SpeedLimit     | The State will change when it enters the speed zone | No                    |
| Mute (input)   | The sensor is silenced when this is active          | Sync Option           |
| Synch Out      | When the sensor is confirmed silenced, this changes | Sync Option           |

## SYSTEM DIAGNOSTICS

The Diagnostics screen allows the user to test the system, activating alarms and outputting set speeds. It is also possible to perform self test of the system and check the status.

Self test will perform the following actions:

- Check internal voltages and compare them to defaults and installation references.
- Check connectivity and connected items.
- Disconnect NMEA ports and loop back to check circuit function.
- Measure function of the sensor (pinging between channels and analyse returning signals).

To test other systems connected to this system, a data test is available, allowing output parameters to be entered and given out on all the activated outputs. In addition, an alarm condition can be simulated and acknowledged. For demonstration, a simulator can be activated to show a recorded data set over time. This function will turn off automatically after 6 hours or on power reset.

Speed simulation is a full check of the system. The speed information is set to the sensor and the sensor produces frequencies corresponding to the desired speed. In this way all parts of the system are in use, and this in itself is a good diagnostic check.

## AVAILABLE OPTIONS IN THE DIAGNOSTIC PAGE

- Simulators
- Speed

In this page it is possible to set a fixed speed and send this to the sensor. This will result in the speed being presented on all displays and outputs. This mode is a full simulator and will verify that all electronics and processing in the system are operational. When active an orange 'S' will show on screen.

- Alarm

By pressing the alarm simulator a typical alarm will become active. this can be acknowledged as normal, and will disappear when the simulator is removed.

## ERROR MESSAGES

The following error cases are accounted for.

| Error description   | How you see it   | Possible fault   |
|---|--|--|
| Data from sensor missing.                                       | On the screen the data disappears and is replaced by '-.-'. Temperature readings will also disappear<br>The status LEDS on JB unit shows constant orange | The sensor is not sending data.<br>Check cabling between sensor and Electronic unit.   |
| Data from sensor wrong  | On the screen the data disappears and is replaced by '-.-'<br>The Status LEDS on JB70 unit will flash orange   | Sensor is not able to measure the speed.   |
| Loss of communication between display unit and electronic unit. | On screen the following status will occur 'Lost communication'<br>The JB70 unit will send a system alarm.  | The pairing between the Display unit and Electronic unit has failed.<br>Check your cabling and check setup. (SKIPPER service software may be used) |

**1 The Display does not connect with the JB70 electronic unit**

(Shows 'NO CONNECTION')

The display connects using a UDP LAN protocol. Both units must be set up to have an ID number and IP address. The skipper service software can be used to simply reassign all these values.

Skipper service software available from the download pages of [www.skipper.no](http://www.skipper.no).

**2 No data from the sensor (the screen shows -,- instead of STW value)**

This can be due to cabling issues to the sensor or sensor failure. Go to the config Diagnostics page, and run a self test. This will report no detected sensor, in this case. most likely problem is wrong cabling, but maybe the voltage is too low for the sensor. Measure the voltage at the junction near the sensor. This voltage should be >15V

If it is lower, remove the cable from the electronic unit and loop the end cable at this point, and measure the loop resistance. It should be according to the specification shown in chapter 2. The vaalues supplied for installation are worst case and the sensor will work normally with a loop resistance of up to 16 ohms.

If the voltage is ok at this point, check the NMEA output of the sensor (Blue/green) to check the sensor is operational. You can also measure current taken by the sensor, it should be in the region of 200mA at 24V (5W) and pulsing higher.

If this is not the case, try connecting a power supply with 24V directly to the sensor (Green +24V, Brown 0V) to see if unit starts.

If all this fails, there may be an error in the sensor.

**SAVING AND LOCKING**

The parameters will be automatically saved and if the the individual units of the system loose communications, they will re-synchroinize when they reconnect.

## HARDWARE OPTIONS

In addition to the mechanical options and software options, it is possible to select hardware options. These require an additional PCB and front plate. See appendix 3.

### 1. Extension card (available soon)

By adding an extension card (already in place in the DL21) it is possible to extend the system to have access to the IO of this card.

As DL21, this will give 2 extra NMEA, 2 analog outputs 1 extra Aux in and Aux out.

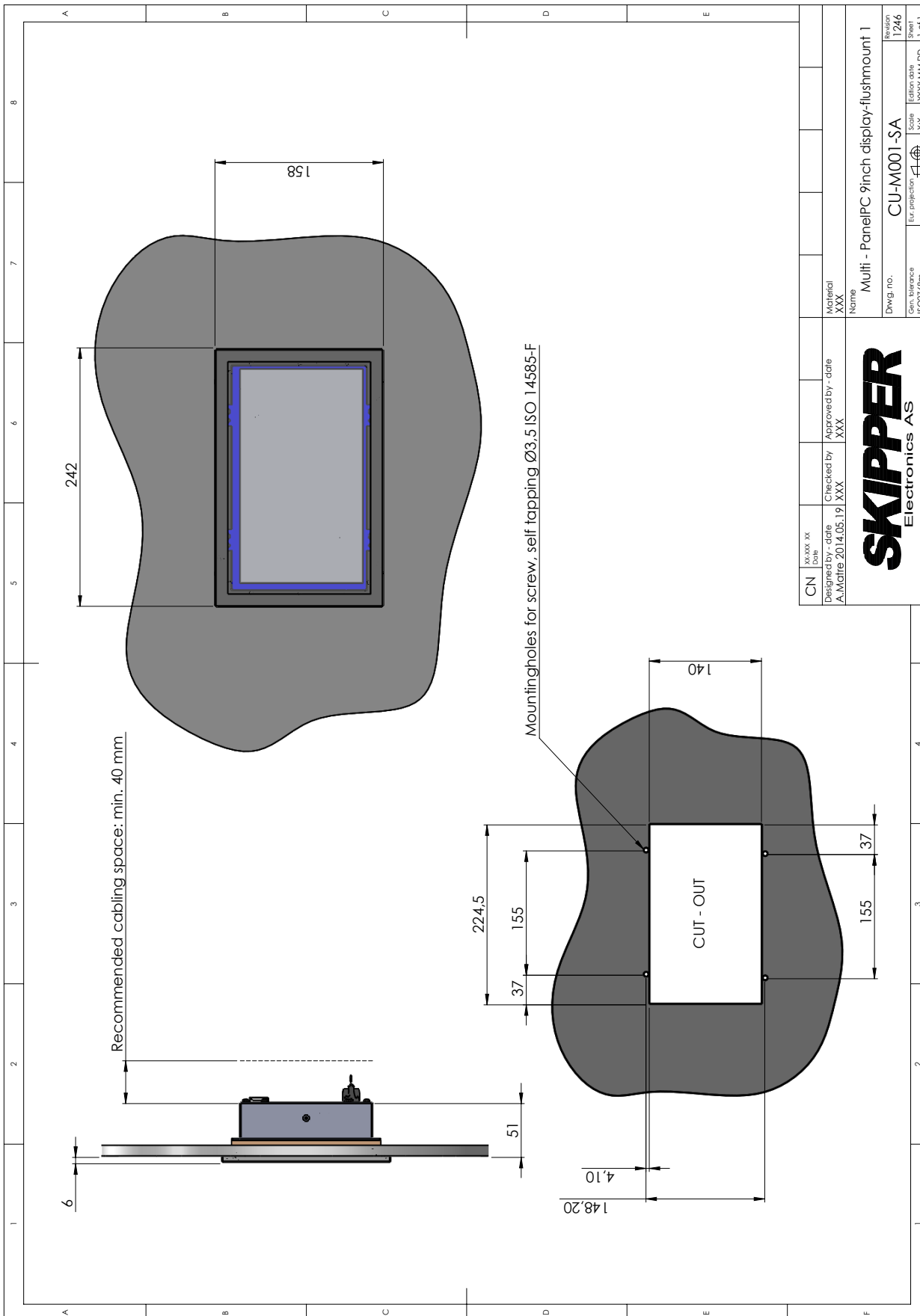
As DL2, this will give 6 extra NMEA outputs(total 10 with 3 channels), 2 Extra NMEA inputs (total 3), 2 analog outputs, 4 extra Aux outputs(Total 7) and 2 extra Aux inputs(total 3)

### 2. Dual system (DL21)

The DL2 (JB70D2 electronic unit) can also be upgraded with an extension card where the card can be used partly as extension (for analogue and extra NMEA outputs (2 extra)), and also as a separate single axis Doppler speed log. In addition to the PCB, an additional sensor or the sensor of type DL21S is required. This sensor contains both 2 axis (270 kHz) transducers, but also a single axis (715 kHz) speed log within the same housing. New regulations for vessels over 50 K GRT (Gross Register Tonnage) state that the vessel must have separate (electrically isolated) systems for speed over ground and speed through water. This system and the use of auxiliary +24 V DC power on the JB70D2-X electronic unit meets this criteria. A CD402CU-XX control unit will also be required for the secondary system.



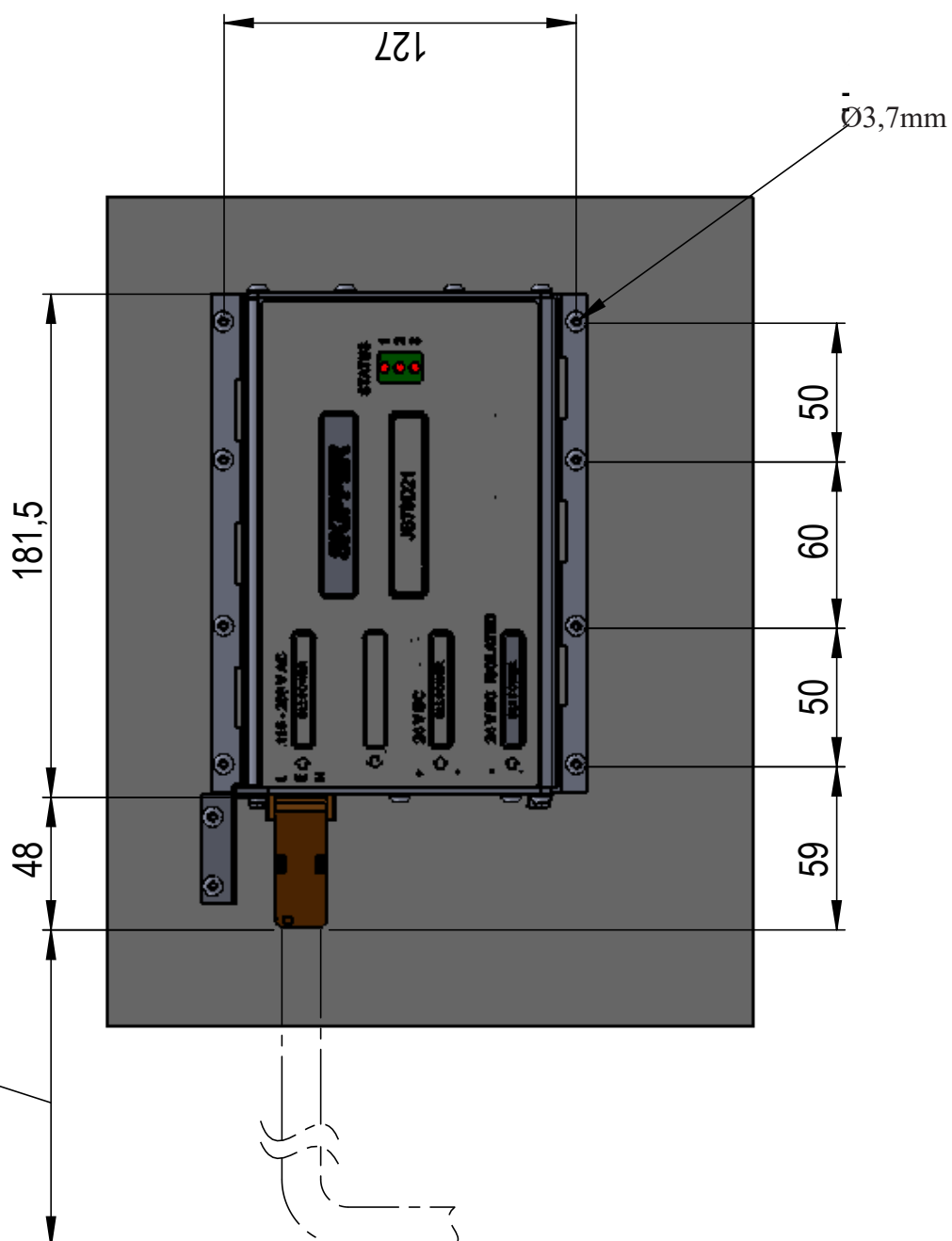
## Operator unit Flushmount dimensions

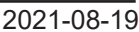


The diagram illustrates the mechanical specifications for the Multi-Panel PC 9-inch display-deskmount 2. It includes three main views: a front view showing the display area (242 mm wide) and mounting bracket (148.50 mm wide), a side view showing the depth (133 mm) and mounting bracket (158 mm), and a perspective view showing the display and mounting bracket. Dimensions are provided in millimeters (mm). The front view shows a display area of 242 mm and a mounting bracket of 148.50 mm. The side view shows a depth of 133 mm and a mounting bracket of 158 mm. The perspective view shows the display and mounting bracket. The table of technical specifications is located at the bottom of the diagram.

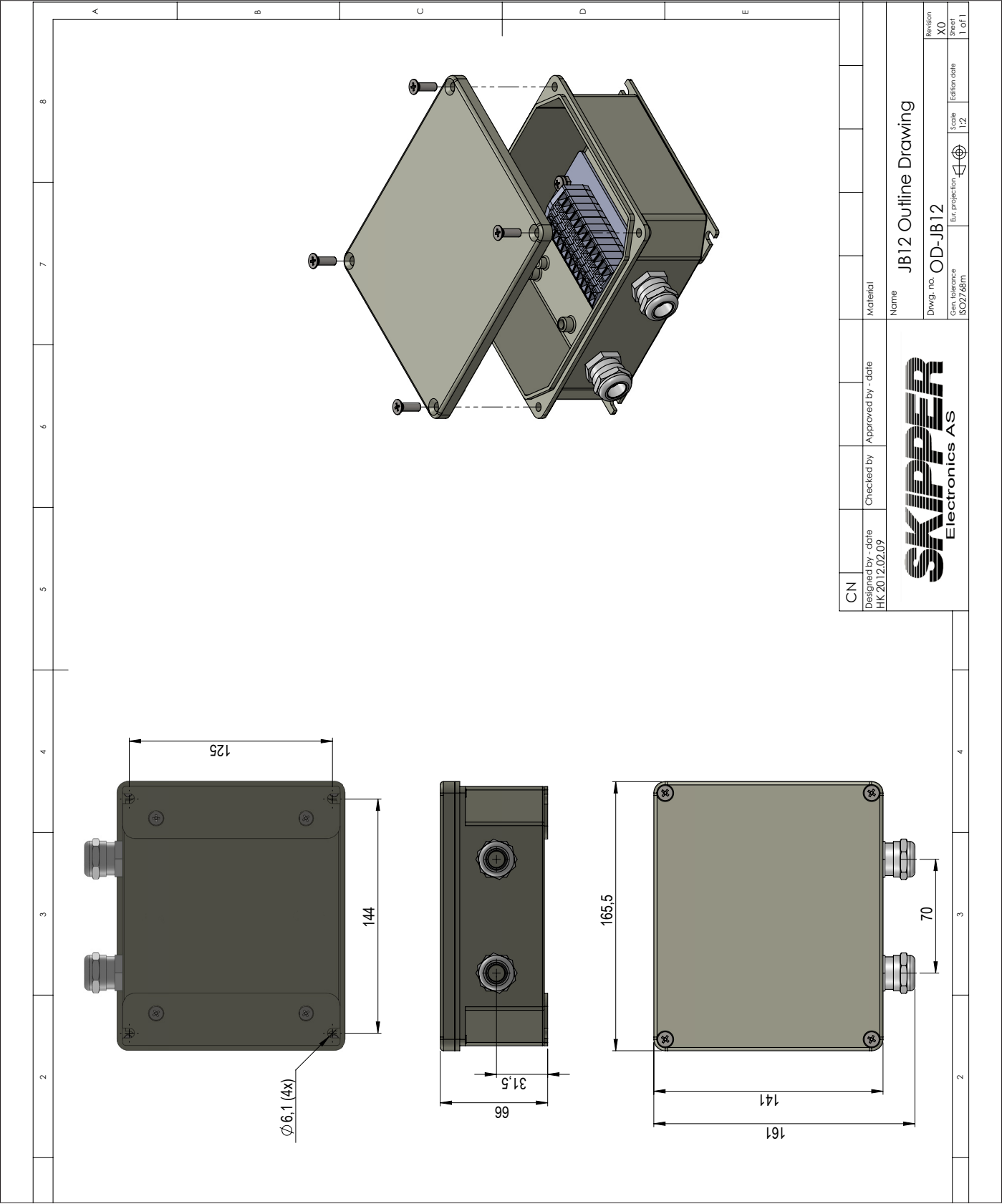
| CN | Rev. XXX XX<br>Date | Designed by - date<br>XXX YYYY.MM.DD | Checked by<br>XXX | Approved by - date<br>XXX | Material<br>XXX | Name   |
|----|---------------------|--------------------------------------|-------------------|---------------------------|-----------------|--|
|    |                     |                                      |                   |                           |                 | Multi-Panel PC 9-inch display-deskmount 2-<br>mechanical diagram |
|    |                     |                                      |                   |                           |                 | Drawg. no. CU-M001-SA  |
|    |                     |                                      |                   |                           |                 | Rev. no. 1246  |
|    |                     |                                      |                   |                           |                 | Scale X:X  |
|    |                     |                                      |                   |                           |                 | Sheet X of X   |
|    |                     |                                      |                   |                           |                 | ISO 2768m  |

Recommended  
minimum free  
space for cabling:  
134mm





Junction box JB12 Dimentional drawings



# APPENDIX 2: DATA SHEETS

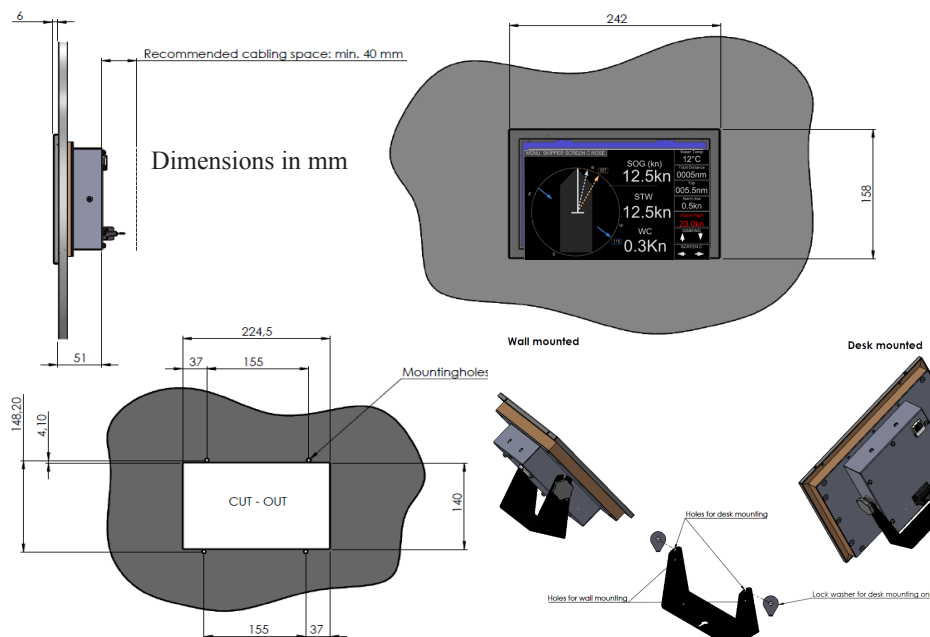
## Product Datasheet

**CU-M001-SB / SD21-SB / SL1200-SB / ESN100-SB / ESN200-SB**

### Multi - PanelPC 9inch touch display

#### Specifications

|                              |   |
|------------------------------|---|
| <b>Description</b>           | Multi - PanelPC 9inch touch display<br>9" Touch display. Resistive touch,<br>Resolution 800 x 480.<br>LED backlight. 400 Nits.<br>Viewing angle 70/70/50/60 degrees<br>Night dimming via touch or NMEA<br>Flush mount, (wall mount or desktop mount option) |
| <b>Input/Output</b>          | 1 LAN. (IEC 61162-450)<br>2 NMEA in. 1 NMEA out. (NMEA 0183, IEC61162-1)<br>1 RS485/RS422 (NMEA use changes per product))<br>Alarm Beeper   |
| <b>Used with</b>             | JB70XX-XX Electronic unit (CU-M001-SB(DL2,DL21), SD21-SA(SD21), ESN200-SB(ESN200))<br>JB40POW-SA Electronic unit (SL1200-SB(SL1200))<br>JB50E1-SA ESN100 Transceiver (ESN100-SB(ESN100))  |
| <b>Package consist of</b>    | 9" Control unit<br>Bracket for desk/wallmount<br>Connector female, Power, NMEA, CAN   |
| <b>Mounting options</b>      | Flush, wall/desk with option MG-0002  |
| <b>Packaging dimensions</b>  | 325 x 125 x 230 mm  |
| <b>Packaging weight</b>      | 1,2 kg  |
| <b>Power consumption</b>     | 12 - 24 V DC, max 10 W, typ 6 W   |
| <b>IP rating</b>             | 22  |
| <b>Operating temperature</b> | -15 to 55°C   |
| <b>Storage temperature</b>   | -20 to 70°C   |
| <b>Humidity</b>              | 10 to 90% relative. No condensation   |
| <b>Manufacturer</b>          | SKIPPER Electronics AS, Norway  |



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[www.skipper.no](http://www.skipper.no)

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Date: 2018.02.21

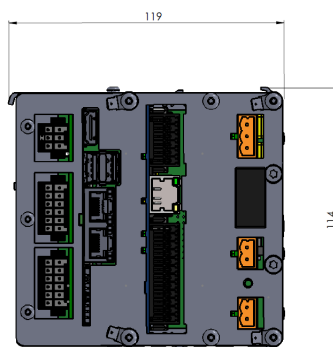
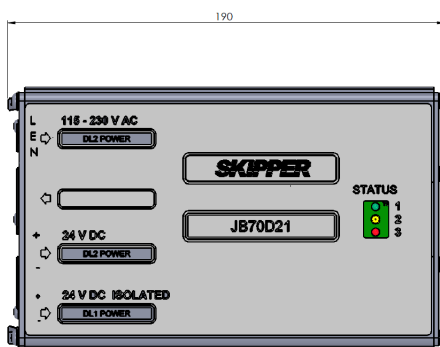
# Product Datasheet

## JB70D21-SA Electronic Unit for combined DL2 and DL1 Doppler Speed Logs

### Specifications

|   | Part number  | Description   |
|---|--|---|
| <b>Part number</b>                                      | JB70D21-SA   | Electronic unit for DL21  |
| <b>Control units</b>                                    | CD402CU-SC<br>CU-M001-SB   | DL1 Multi Control unit with LAN<br>DL2 Control unit 9" Touch display  |
| <b>Sensor</b>   | DL21SG-SA  | 1 axis STW and electronic separated 2-axis SOG  |
| <b>JB70D21-SA<br/>Package consist of</b>                | JB70D21-SA<br>M-KIT-JB70XX   | Electronic unit for DL21<br>Mounting kit for JB70   |
| <b>PCBs inside<br/>JB70D21-SA</b>                       | PP-M001<br>PI-M001<br>PC-M001-21   | Multi power, PCBM<br>DL1 processor, PCBM<br>DL21 main processor, PCBM   |
| <b>PP-M001 power</b>                                    | 115 - 230 V AC/24 V DC max 60 W (For DL2) typ.<br>15 W<br>24 V DC max 20 W (for DL1) typ. 10 W   | Dual isolated power supply.   |
| <b>PI-M001 interfaces<br/>for DL1 Multi</b>             | <ul style="list-style-type: none"> <li>NMEA0183, IEC61162-1, 4 output, 1 input</li> <li>Auxiliary x 3 output, 2 input</li> <li>Alarm relay x 1</li> <li>Analogue 1 x 0-10 V, 1 x 4-20 mA</li> <li>LAN IEC 61162-450 fully implemented. for communication with display module and/or web page setup.</li> </ul> | <ul style="list-style-type: none"> <li>NMEA outputs can be used for IEC61162-2</li> <li>Auxiliary can be designated to alarm, pulse, speed warning</li> <li>Relay designated to function and/or powerfailure alarm</li> <li>Configurable web pages for setup and runtime functions</li> </ul> |
| <b>PC-M001-21<br/>Interfaces for DL2 in<br/>JB70D21</b> | <ul style="list-style-type: none"> <li>NMEA 0183, IEC61162-1, 2 output, 1 input</li> <li>Auxiliary x 2 output, 1 input</li> <li>Alarm relay x 1</li> <li>2 x LAN IEC 61162-450</li> </ul>  | <ul style="list-style-type: none"> <li>Auxiliary can be designated to alarm, pulse, speed warning</li> <li>Relay designated to function and/or powerfailure alarm</li> </ul>  |
| <b>IP rating</b>  | IP 20  |   |
| <b>Operating temperature</b>                            | -15 to 55°C  |   |
| <b>Storage temperature</b>                              | -20 to 70°C  |   |
| <b>Humidity</b>   | 10 to 90 % relative. No condensation   |   |
| <b>Weight</b>   | 1.5 kg   |   |
| <b>Packaging dimensions / weight</b>                    | 30.5 x 21.5 x 21 cm / 2 kg   |   |
| <b>Manufacturer</b>                                     | SKIPPER Electronics AS, Norway   |   |

Dimensions in mm

**SKIPPER**

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Date: 2019-03-08

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## Data sheet DL21SG-SA

# Product Datasheet

## DL21SG-SA Log sensor DL21

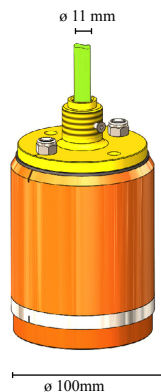
### For 100mm Sea valve SB-100-XX/DB100-XX

#### Specifications

|                              | Part number            | Description/units  |
|------------------------------|------------------------|--|
| Part number                  | DL21SG-SA              | <ul style="list-style-type: none"> <li>Log sensor DL21 SKIPPER for 100mm Sea Valve</li> <li>1 Doppler sensor 1-axis STW</li> <li>1 Doppler sensor 2-axis STW+SOG</li> <li>The 2 sensors mounted in one bottom mounting works independantly and are electrically isolated</li> <li>Designed for ships over 50.000 GRT with simultaneous and independent measurement of speed through water (STW) and speed over ground (SOG)</li> </ul> |
| To be installed into         | SB-100-XX<br>DB-100-XX | Sea Valve 100 mm , Single Bottom SST<br>Sea Valve 100 mm, Double Bottom SST  |
| To be used with              | JB70D21-XX             | Electronic unit  |
| Acoustic frequency range     |                        | 270-284 kHz (STW+SOG), 710-720kHz (STW)  |
| Bottom detection (SOG)       |                        | < 200 m  |
| Cable length                 |                        | 40 m (may be extended or shortened)  |
| Cable diameter               |                        | 11 mm +/-0.5   |
| Cable minimum bending radius |                        | 56 mm  |
| Accuracy                     |                        | 0.2 kn or 2 % whichever is greater   |
| Speed resolution             |                        | 0.1 kn   |
| Max speed                    |                        | +45 to - 10 kn Longitudal<br>+/- 25knot Transversal  |
| Temperature accuracy         |                        | 1 deg  |
| Temperature resolution       |                        | 0.1 deg  |
| IP rating                    |                        | IP 68  |
| Operating temperature        |                        | -15 to 55°C  |
| Storage temperature          |                        | -20 to 70°C  |
| Depth rating                 |                        | 6 bar  |
| Outputs                      |                        | 2 x NMEA (proprietary formats) RS422   |
| Input                        |                        | 2 x NMEA (proprietary formats) RS422   |
| Power input                  |                        | 2 x Nom. 24 V (18 V to 32 V) 16 W  |
| Weight                       |                        | 10.2 kg  |
| Manufacturer                 |                        | SKIPPER Electronics AS, Norway   |



137mm


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 Date: 2015-02-23

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## APPENDIX 4: COMMISIONING CHECKLIST

| Test Nr  | Task  | Test to be performed  | Checklist |
|----------|---|---|-----------|
| DL2 – 1  | Wire and check the system   | Wire together the JB70 LAN and CU-M001 Graphic display  |           |
| DL2 – 2  |   | • Display does not show 'NO COMMUNICATION'  |           |
| DL2 – 3  |   | Set up the config as per instructions   |           |
| DL2 – 4  | Wire NMEA IN, NMEA OUT  | Wire NMEA IN, NMEA OUT  |           |
| DL2 – 5  |   | • MFD shows VBW,x.x,y.y,A,x   |           |
| DL2 – 6  |   | • MFD shows .x,y,y,A,,A,z.z,A , MTW, VLW  |           |
|          |   | Wire Relay output J2 to common alarm  |           |
|          |   | • Remove power (AC and DC) and check you see alarm  |           |
| DL2 – 4  | Install and connect sensor for DL2 to the JB70 unit (J3)<br>Connect JB70 to CU-M001 display<br>Check Sensor | Check Using the service software and the self test in Config – Diagnostic – Self test,                    |           |
| DL2 – 5  |   | • Serial Number of sensor (DL2) should be same as on cable  |           |
| DL2 – 6  |   | • Firmware version should be correct (3.00 or greater)  |           |
|          |   | • Live data should show quality factor (QF) 8 or 9  |           |
|          |   | Upgrade firmware to the version on the skipper websites   |           |
| DL2 – 9  | Install setup in the Bridge Conning system  | Check on MFD that you see inputs from DL2   |           |
| DL2 – 10 |   | • You can see input VBW, VLW, MTW, occasional VDALR, Check on MFD that you can see the Outputs to the Log |           |
|          |   | • You can see VTG, DPT, GGA, occasional ACK   |           |
| DL2 – 11 |   | Check NMEA 1/2 input  |           |
| DL2-12   |   | Check on display – Config – Communication, that the input is showing GYRO and GPS information.            |           |
|          |   | • Can see HDT/THS, ROT, VTG,GGA/GLL   |           |
|          |   | • Can see aft speed on page D   |           |

A large, stylized logo of the word "SKIPPER" in a bold, italicized font. The letters are filled with horizontal black and white stripes, giving it a dynamic, speed-related appearance.

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